Understanding Computation with Computation

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Algorithm synthesis

- Computer science: what can be automated?
- Can we automate our own work?
- Can we outsource algorithm design to computers?
 - input: problem specification
 - output: asymptotically optimal algorithm

Verification and synthesis

Verification:

- given problem P and algorithm A
- does A solve P?

Synthesis:

- given problem P
- find an algorithm A that solves P?

Verification and synthesis

- Algorithm verification often difficult
 - easy to run into e.g. halting problem
- Algorithm synthesis is entirely hopeless?
- Not necessarily!
 - verifying arbitrary algorithms in model M
 - synthesising only "nice" algorithms in model M

Setting

- Our focus: distributed algorithms
 - multiple nodes working in parallel
 - complicated interactions between nodes
 - possibly also faulty nodes, adversarial behaviour
- Computational techniques in algorithm design can outperform human beings

Setting

- We do theory, not practice
- Desired outputs:
 - algorithm design & analysis
 - lower-bound proofs
- We want provably correct algorithms, not something that "seems to work"

Success stories (1/4)

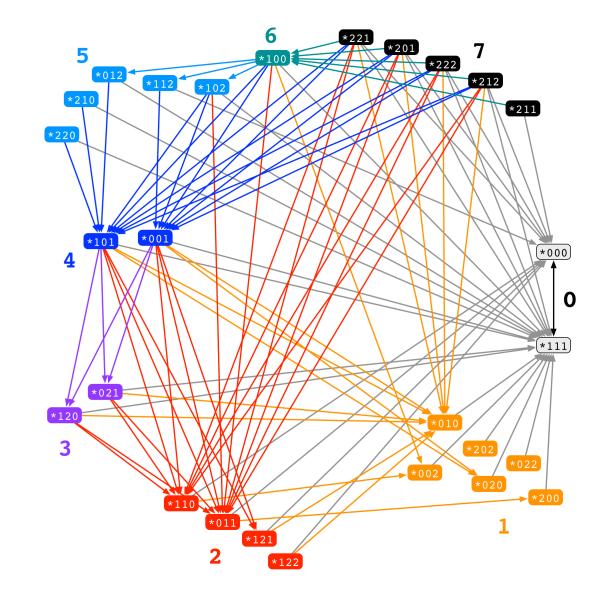
- Fault-tolerant digital clock synchronisation
 - nodes have to count clock pulses modulo c
 - self-stabilising algorithms: reaches correct behaviour even if the starting state is arbitrary
 - Byzantine fault tolerance: some nodes may be adversarial

4 nodes

1 faulty node

3 states per node

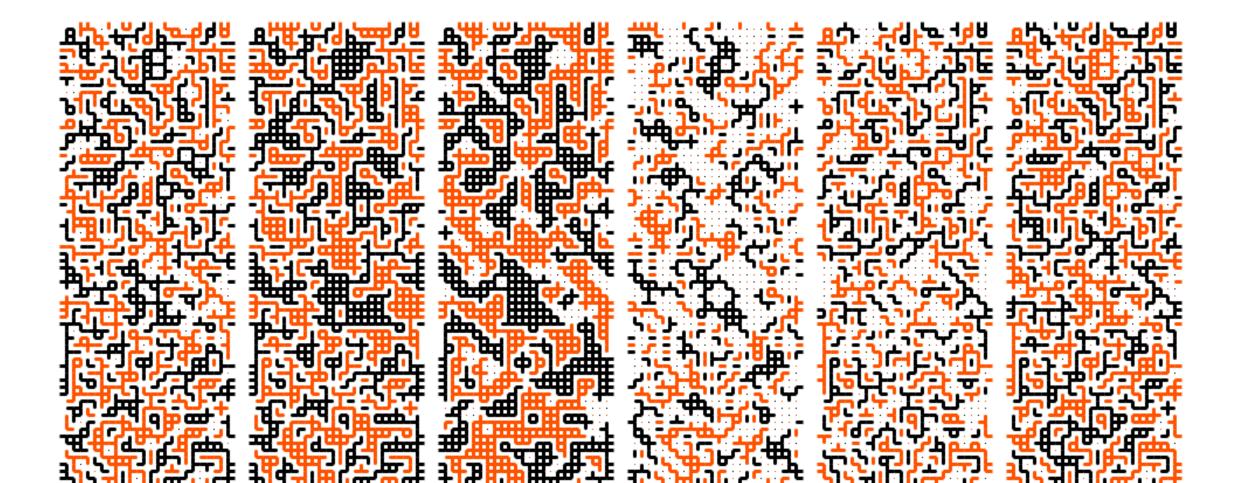
always stabilises in at most 7 steps



Success stories (2/4)

- Theorem: any triangle-free *d*-regular graph has a cut of size $\left(\frac{1}{2} + \frac{0.281}{\sqrt{d}}\right)m$
 - prior bound: $\left(\frac{1}{2} + \frac{0.177}{\sqrt{d}}\right) m$ (Shearer 1992)
- Proof: we design a simple randomised distributed algorithm that finds such cuts (in expectation)

Pick a random cut, change sides if at least $\left[\frac{d+\sqrt{d}}{2}\right]$ neighbours on the same side

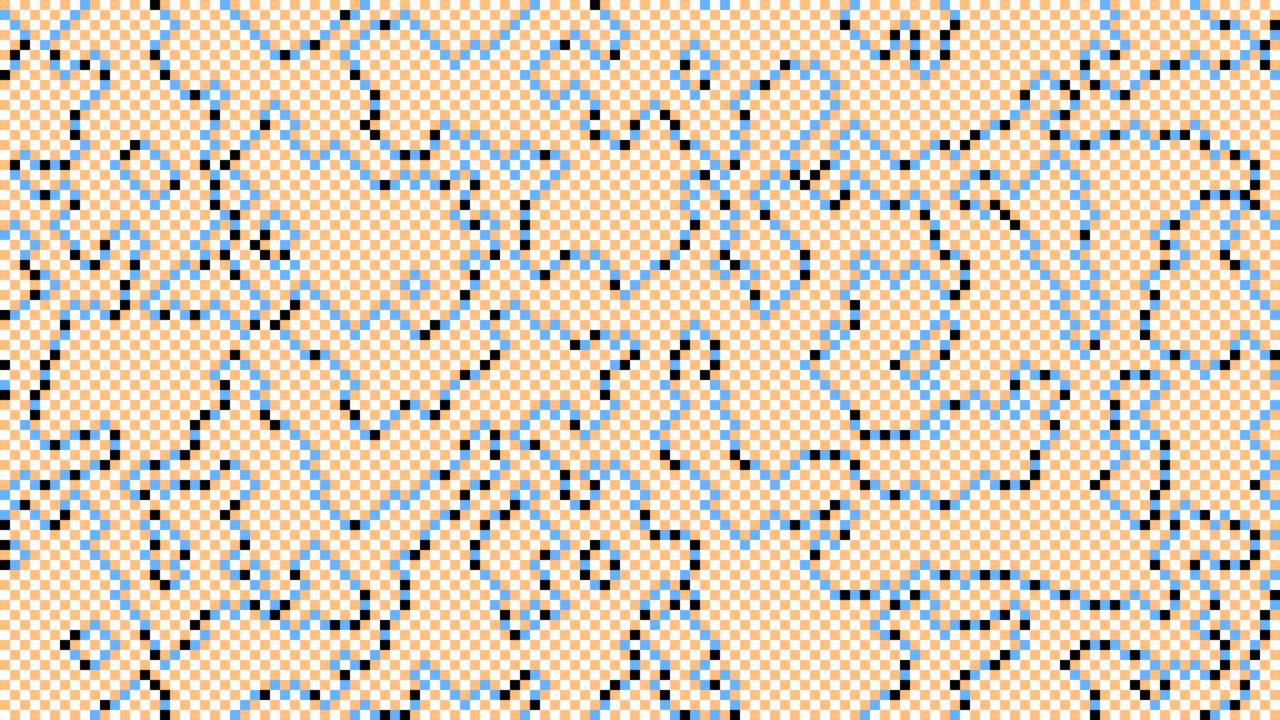


Success stories (3/4)

- Classical symmetry-breaking primitive:
 - input: directed path coloured with n colours
 - output: directed path coloured with 3 colours
- Prior work: $\frac{1}{2} \log^*(n) \pm O(1)$ rounds
- New result: exactly ½ log*(n) rounds for infinitely many n

Success stories (4/4)

- Any locally checkable labelling problem
 - maximal independent set, colouring ...
- Setting: cycles, 2-dimensional grids, ...
- Complexity is O(1), $\Theta(\log^* n)$, or $\Theta(n)$
- Synthesis possible for class Θ(log* n)



Key challenges

- A combinatorial search problem
 - find an object A that satisfies these constraints...
- How to make the problem finite?
 - so that the problem is solvable at least in principle
- How to solve it in practice?
 - how to avoid combinatorial explosion

Key challenges

- Much easier to make the problem finite if we fix some parameters:
 - algorithm for n = 10 nodes?
 - algorithm for any n, but maximum degree $\Delta = 10$?
- How to generalise?

How to generalise

1. Computer-inspired algorithms

computer solves small cases, generalise the idea

2. Generalise by induction

• computer solves the base case, prove inductive step

3. Direct synthesis for the general case

sit down and relax

How to generalise

1. Computer-inspired algorithms

example: large cuts

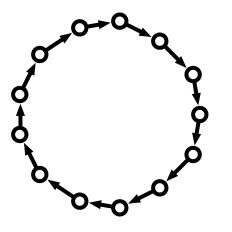
2. Generalise by induction

• example: clock synchronisation

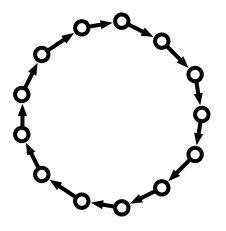
3. Direct synthesis for the general case

example: O(log* n)-time algorithms

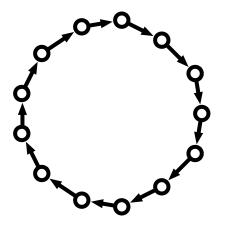
- Computer network = directed *n*-cycle
 - nodes labelled with O(log n)-bit identifiers
 - each round: each node exchanges (arbitrarily large)
 messages with its neighbours and updates its state
 - each node has to output its own part of the solution
 - time = number of rounds until all nodes stop
 - equivalently: time = distance (how far to look)



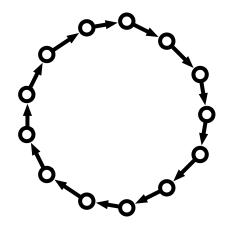
- LCL problems:
 - solution is globally good if it looks good in all local neighbourhoods
 - examples: vertex colouring, edge colouring, maximal independent set, maximal matching...
 - cf. class NP: solution easy to verify, not necessarily easy to find



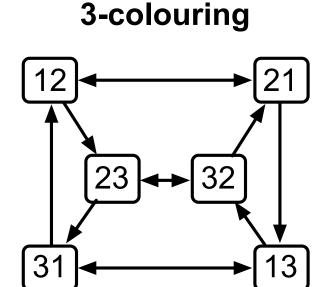
- 2-colouring: inherently global
 - **Θ**(*n*) rounds
- 3-colouring: local
 - $\Theta(\log^* n)$ rounds



- Given an algorithm, it may be very difficult to verify
 - easy to encode e.g. halting problem
 - running time can be any function of n
- However, given an LCL problem, it is very easy to synthesise optimal algorithms!

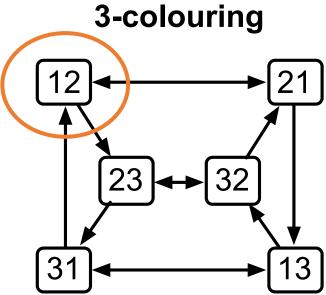


- LCL problem ≈ set of feasible local neighbourhoods in the solution
- Can be encoded as a graph:
 - node = neighbourhood
 - edge = "compatible" neighbourhoods
 - walk ≈ sliding window

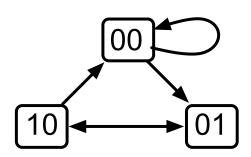


Neighbourhood v is "flexible" if for all sufficiently large k there is a walk $v \rightarrow v$ of length k

- equivalent: there are walks of coprime lengths
- "12" is flexible here, $k \ge 2$

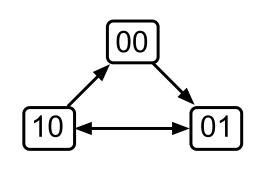


independent set

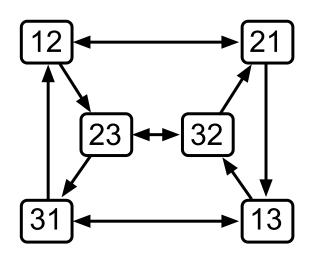


self-loops: O(1)

maximal independent set

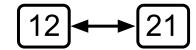


3-colouring



flexible states: $\Theta(\log^* n)$

2-colouring

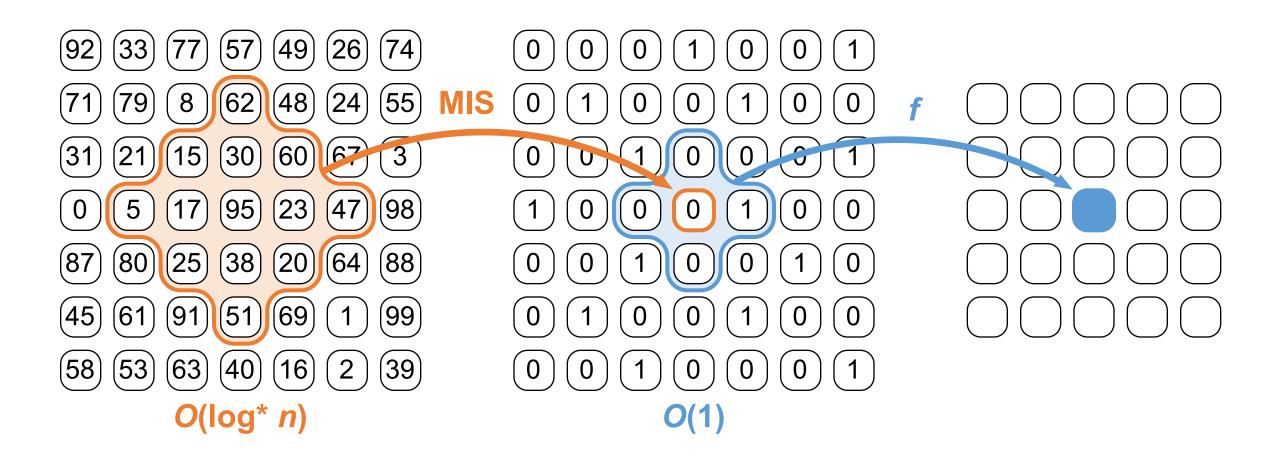


otherwise: $\Theta(n)$

- Verification hard but synthesis easy:
 - construct graph, analyse its structure
- "Compactification":
 - any LCL problem can be represented concisely as a graph
 - seemingly open-ended problem of finding an efficient algorithm is reduced to a simple graph problem

Beyond cycles

- Classification undecidable on 2D grids
 - "is this problem solvable in O(log* n)"
- But 1 bit of advice is enough!
 - just tell me whether it is solvable in time $O(\log^* n)$
 - then I can find an optimal algorithm at least in principle, but often also in practice
 - key insight: "normal form" for any such algorithm



Future

- How far can we push these techniques?
 - immediate next steps: distributed algorithms in much more general graph families
- More focus on meta-algorithmics?
 - how to design algorithms for designing algorithms
- Algorithms for lower bounds?

