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Locality

in online, dynamic,
sequential, and distributed
graph algorithms

Joint work with:

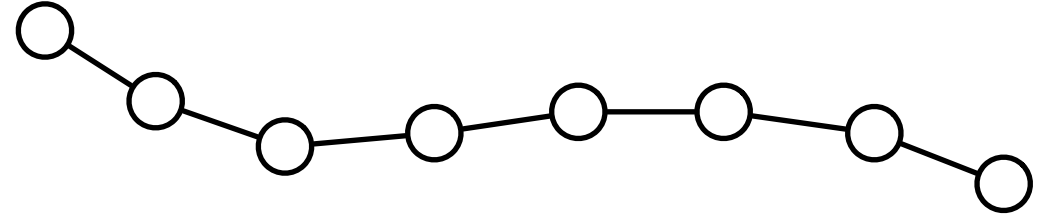
- Amirreza Akbari
- Navid Eslami
- Henrik Lievonen
- Darya Melnyk
- Joonas Särkijärvi

arxiv.org/abs/2109.06593

***Informal
introduction
to locality***

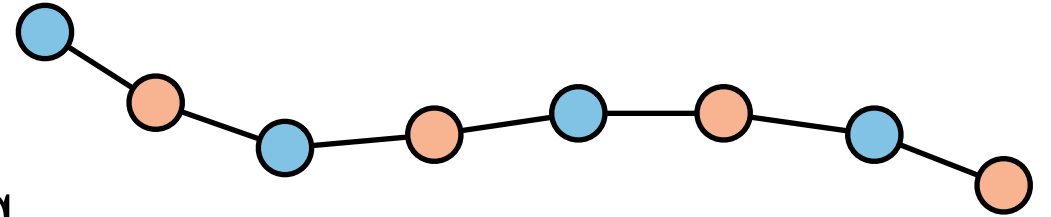
Coloring paths locally?

- **Given:** a path graph



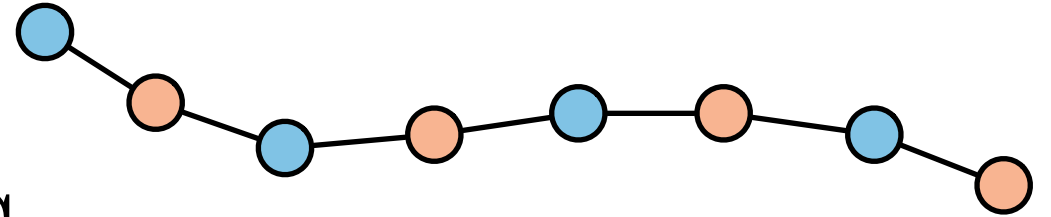
Coloring paths locally?

- **Given:** a path graph
- **Find:** a proper 2-coloring



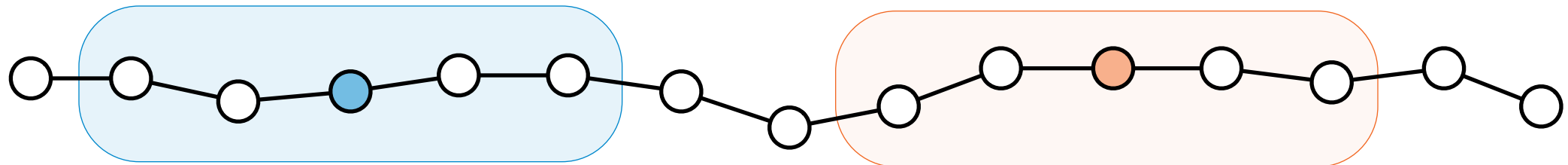
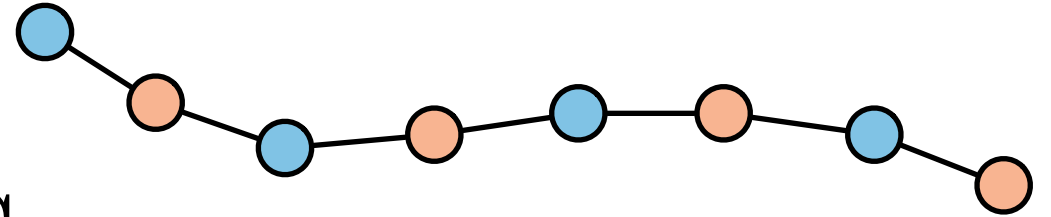
Coloring paths locally?

- **Given:** a path graph
- **Find:** a proper 2-coloring
- **Restriction:** the color of each node *only depends on its local neighborhood*
 - say, radius- $o(n)$ neighborhood



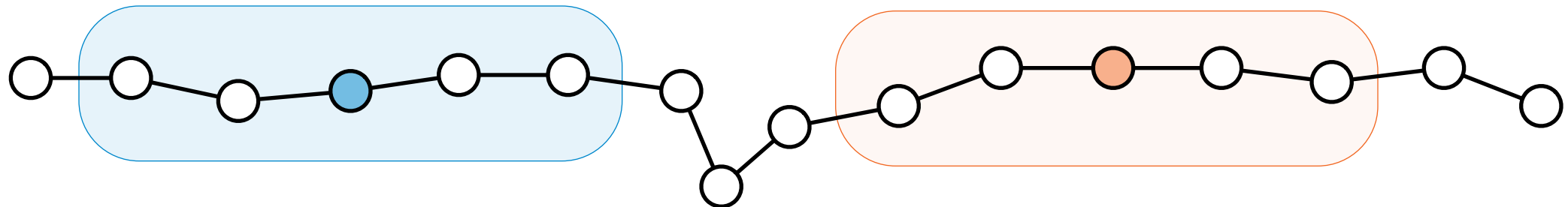
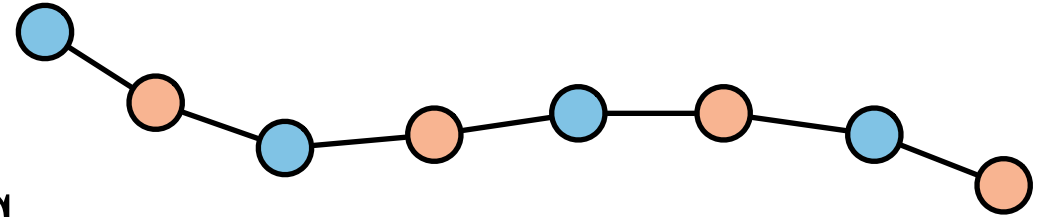
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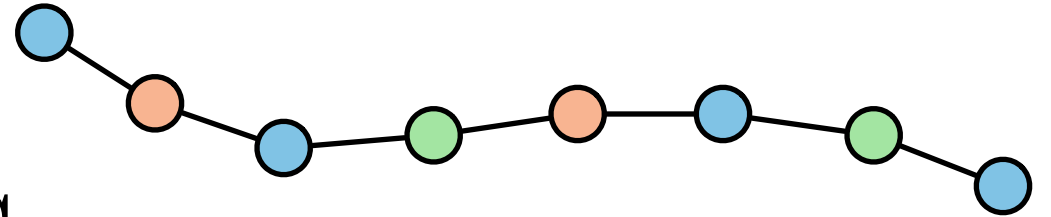
Conclusion:

**Paths can't be 2-colored
with any local strategy**

... and it doesn't really depend on
exactly how we define "local"

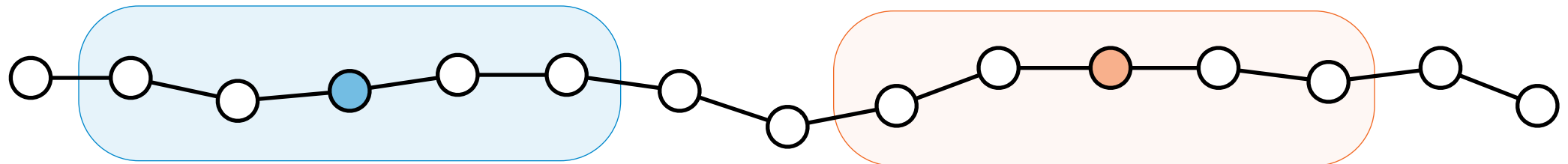
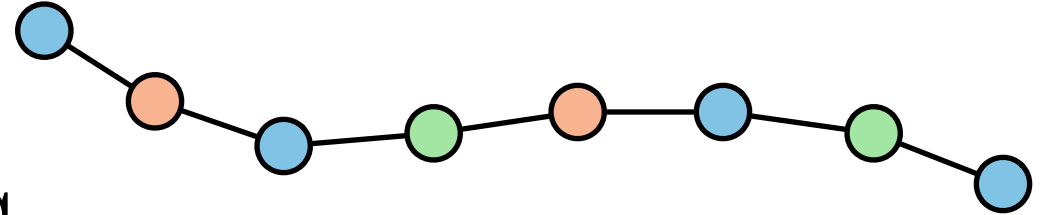
3-coloring paths locally?

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- **Find:** a proper 3-coloring
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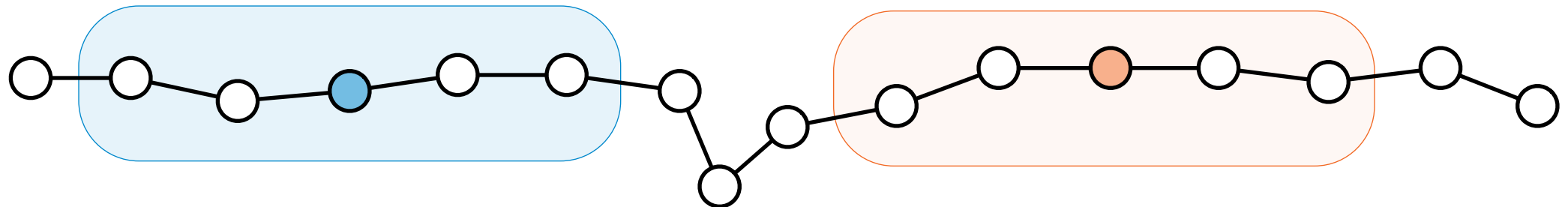
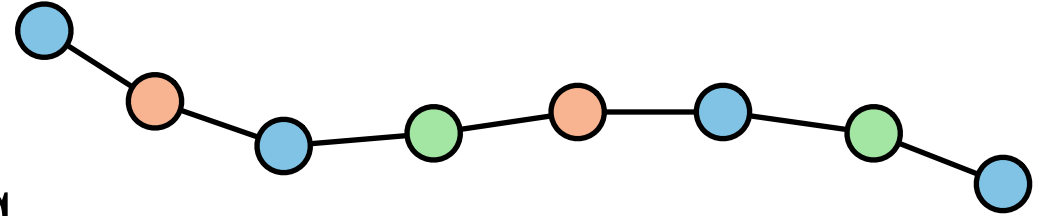
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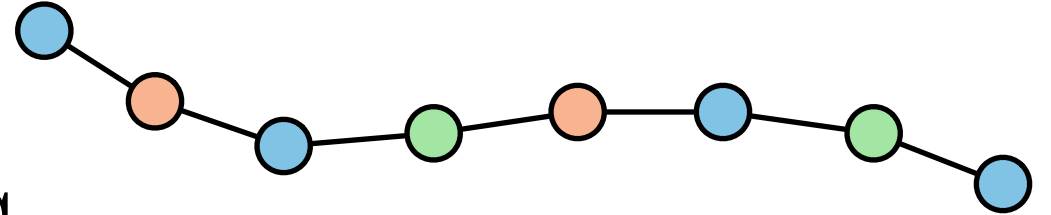
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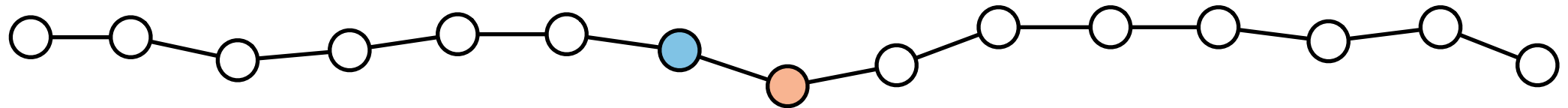
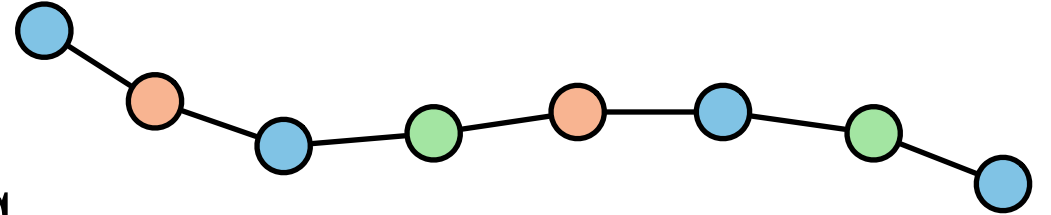
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Conclusion:

**We need some way
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- randomness
- unique node identifiers
- sequential ordering ...

3-coloring paths locally

Nodes labeled with (small) unique identifiers:

$$\text{locality} \approx \frac{1}{2} \log^* n$$

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[Cole & Vishkin 1986, Linial 1992, Naor 1991]

Four models of computing

SLOCAL

distributed,
sequential

LOCAL

distributed,
parallel

**online
LOCAL**

centralized

**dynamic
LOCAL**

centralized

LOCAL
distributed,
parallel

SLOCAL
distributed,
sequential

online
LOCAL
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dynamic
LOCAL
centralized

LOCAL
distributed,
parallel

Each node **in parallel**:

- looks at its radius- T neighborhood
- picks its output based on this information

(nodes have unique identifiers)

LOCAL
distributed,
parallel

SLOCAL
distributed,
sequential

online
LOCAL
centralized

dynamic
LOCAL
centralized

SLOCAL

distributed,
sequential

LOCAL

distributed,
parallel

online

LOCAL

centralized

dynamic

LOCAL

centralized

SLOCAL

distributed,
sequential

Each node in a **sequential, adversarial order**:

- looks at its radius- T neighborhood
- picks its output & state based on this information

SLOCAL

distributed,
sequential

LOCAL

distributed,
parallel

online

LOCAL

centralized

dynamic

LOCAL

centralized

SLOCAL

distributed,
sequential

LOCAL

distributed,
parallel

online

LOCAL

centralized

dynamic

LOCAL

centralized

Graph **constructed** by an adversary that adds nodes and edges one by one

We can **see everything**

We can **change** our output only within distance T from a point of change

dynamic
LOCAL
centralized

SLOCAL

distributed,
sequential

LOCAL

distributed,
parallel

online

LOCAL

centralized

dynamic

LOCAL

centralized

SLOCAL

distributed,
sequential

LOCAL

distributed,
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**online
LOCAL**

centralized

**dynamic
LOCAL**

centralized

Some unknown input graph is **revealed** piece by piece:

- adversary points at a node v
- we can see the radius- T neighborhood of v
- we have to choose the label for v

We can **remember** everything

online
LOCAL
centralized

SLOCAL

distributed,
sequential

LOCAL

distributed,
parallel

**online
LOCAL**

centralized

**dynamic
LOCAL**

centralized

***Genuinely
different
models***

SLOCAL

distributed,
sequential

LOCAL

distributed,
parallel

**online
LOCAL**

centralized

**dynamic
LOCAL**

centralized

coloring

SLOCAL

distributed,
sequential

LOCAL

distributed,
parallel

**online
LOCAL**

centralized

**dynamic
LOCAL**

centralized

coloring

SLOCAL

distributed,
sequential

LOCAL

distributed,
parallel

**online
LOCAL**

centralized

cycle
detection

**dynamic
LOCAL**

centralized

SLOCAL

distributed,
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coloring

LOCAL

distributed,
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**online
LOCAL**

centralized

**dynamic
LOCAL**

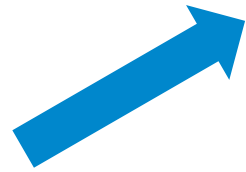
centralized

cycle
detection

leader
election

***Closely
related
models***

LOCAL
distributed,
parallel

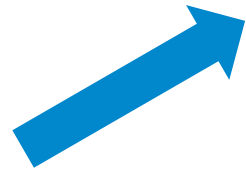


SLOCAL
distributed,
sequential

dynamic
LOCAL
centralized

online
LOCAL
centralized

LOCAL
distributed,
parallel

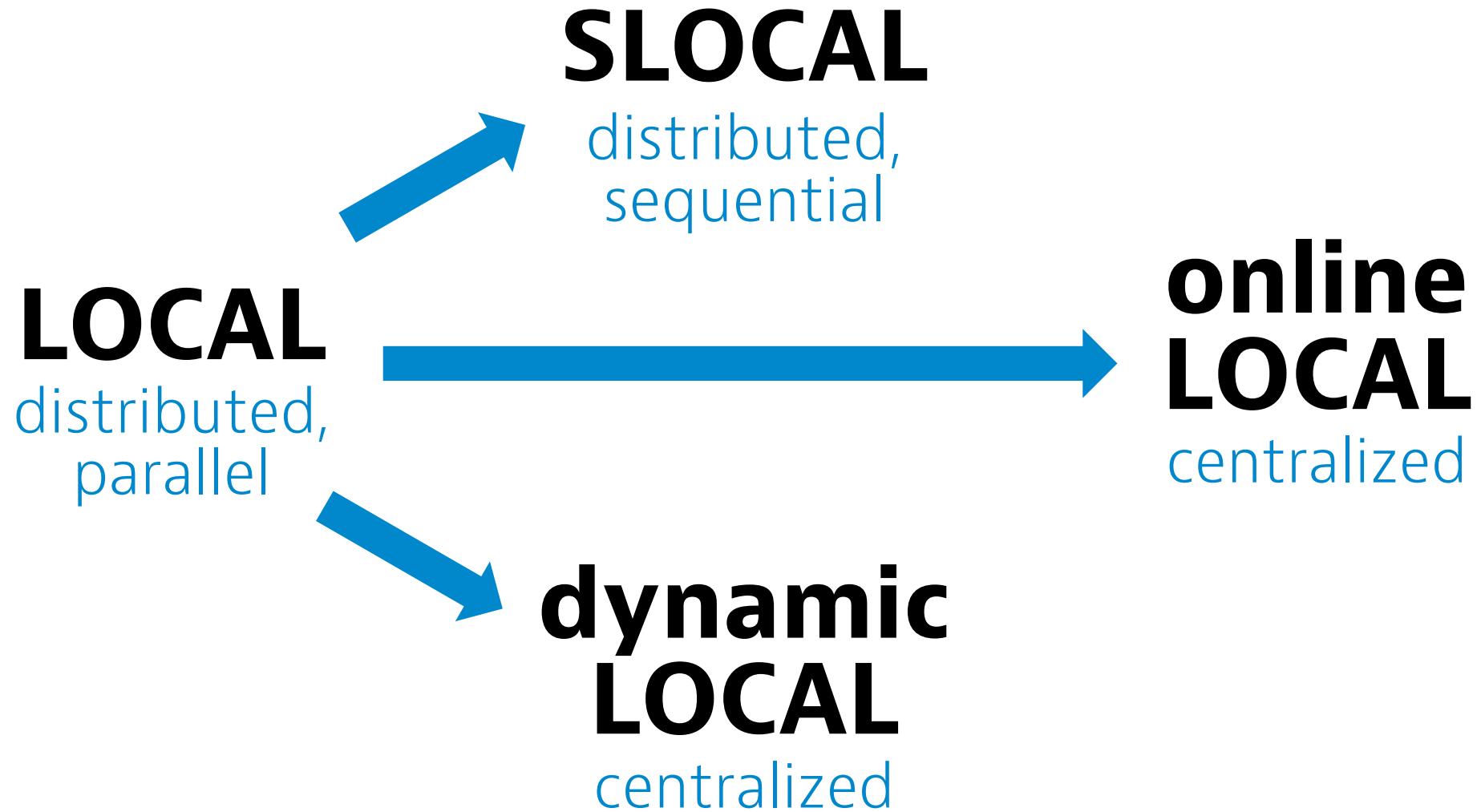


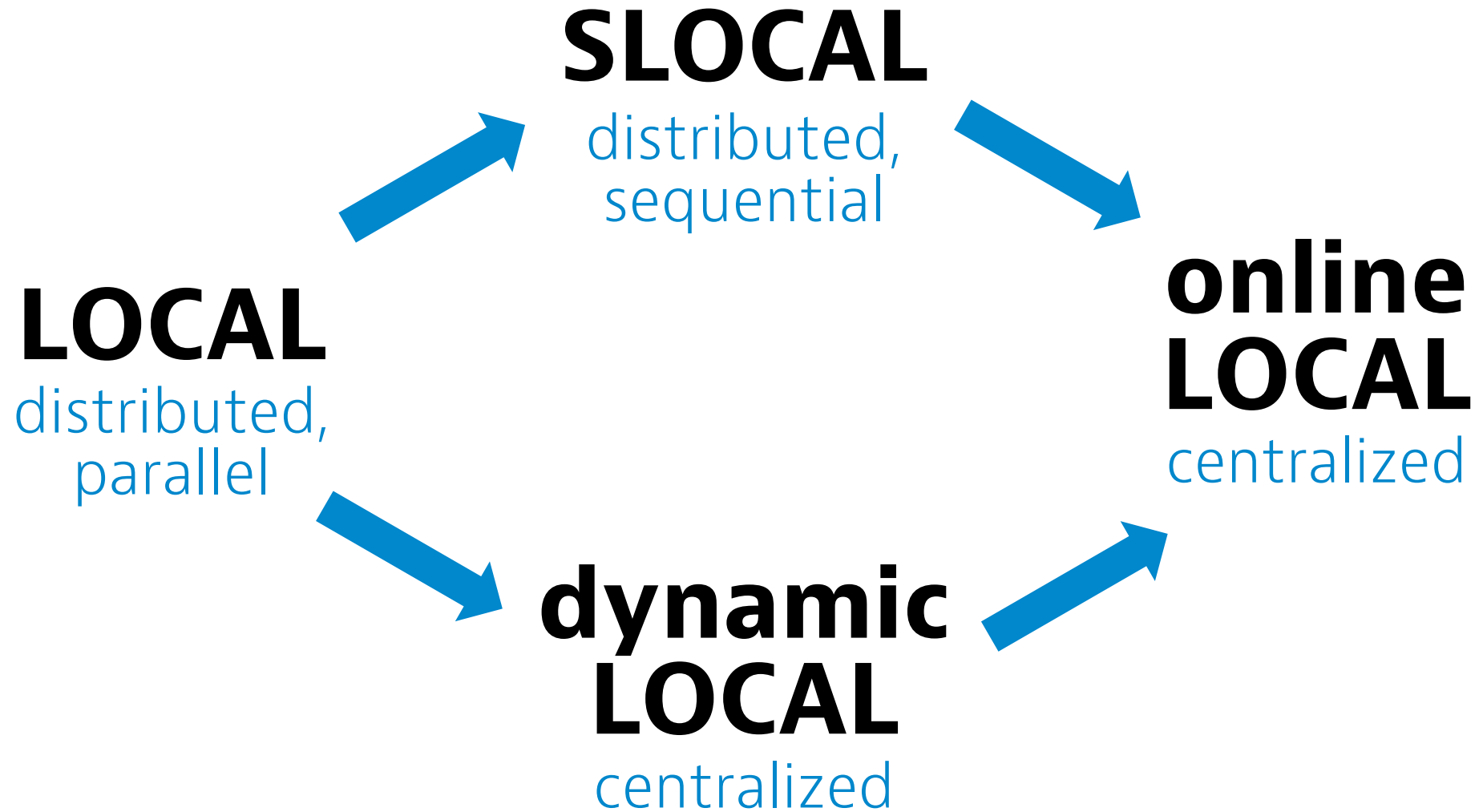
SLOCAL
distributed,
sequential

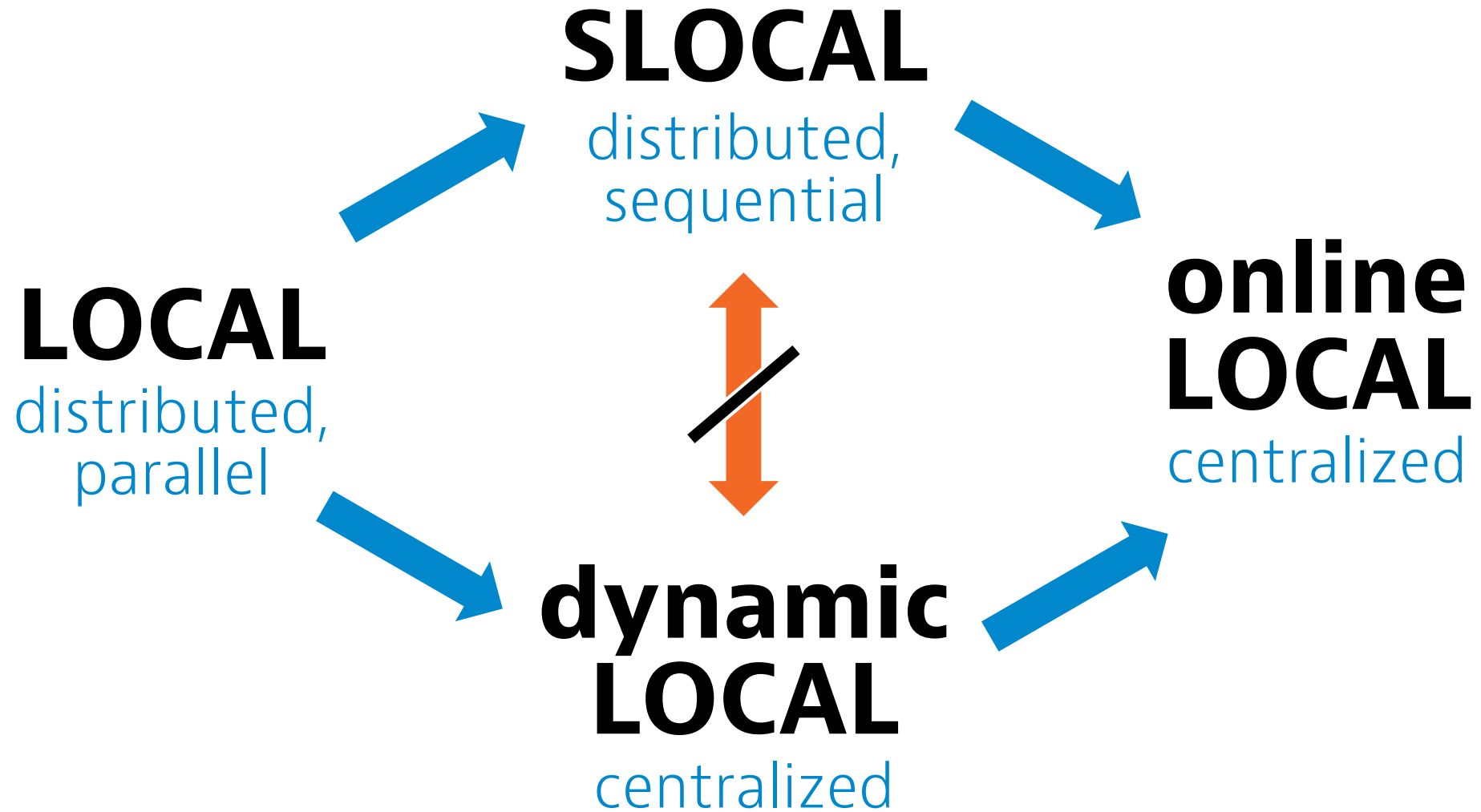


**dynamic
LOCAL**
centralized

**online
LOCAL**
centralized







Collapse in rooted trees

LCLs in rooted trees

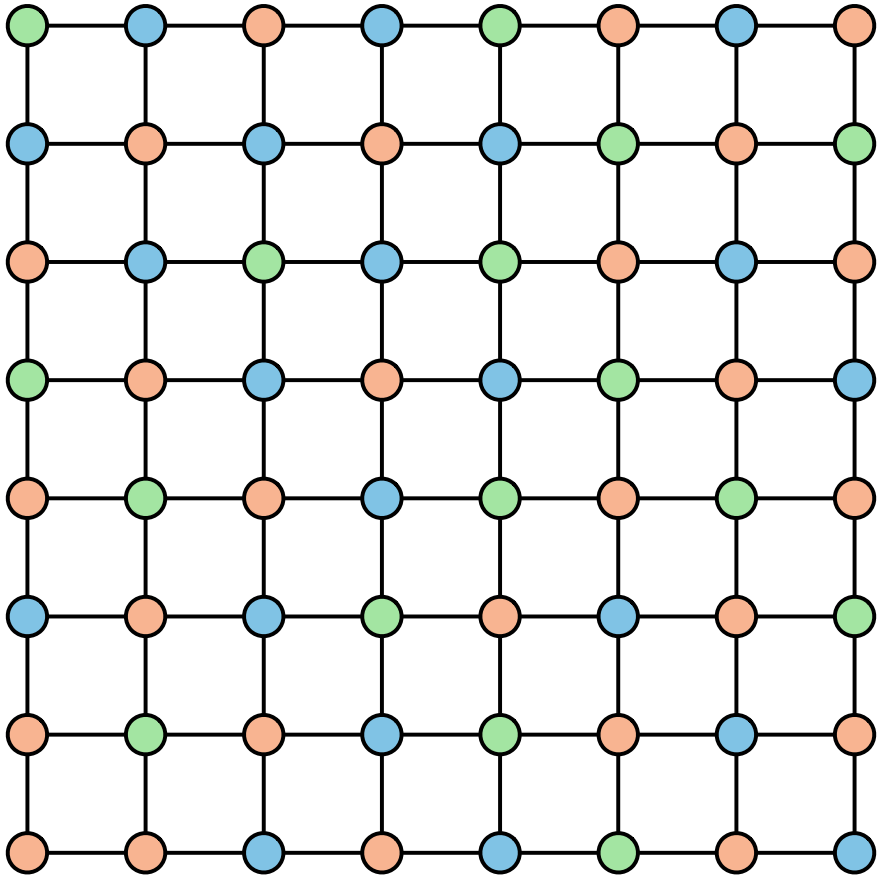
- **Rooted regular trees**
- **Locally checkable labelings** (LCLs)
 - solution valid if it “looks good everywhere”
 - example: 3-coloring
- *In this setting all models equally strong!*

LCLs in rooted trees



Case study: grids

Coloring grids



Coloring grids

- **5-coloring:** local in all models (easy to see)

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- **4-coloring:** local in all models (hard to see)

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 - **online-LOCAL: $O(\log n)$**

Coloring grids

- **5-coloring:** local in all models (easy to see)
- **4-coloring:** local in all models (hard to see)
- **3-coloring:**
 - LOCAL, SLOCAL: global
 - online-LOCAL: $O(\log n)$ — **is this tight?**

Coloring grids

- **5-coloring:** local in all models (easy to see)
- **4-coloring:** local in all models (hard to see)
- **3-coloring:**
 - LOCAL, SLOCAL: global
 - online-LOCAL: $O(\log n)$ — **is this tight?**
 - dynamic-LOCAL: **open**

