Locality in Networks

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1. Locality and Local Algorithms

brief introduction

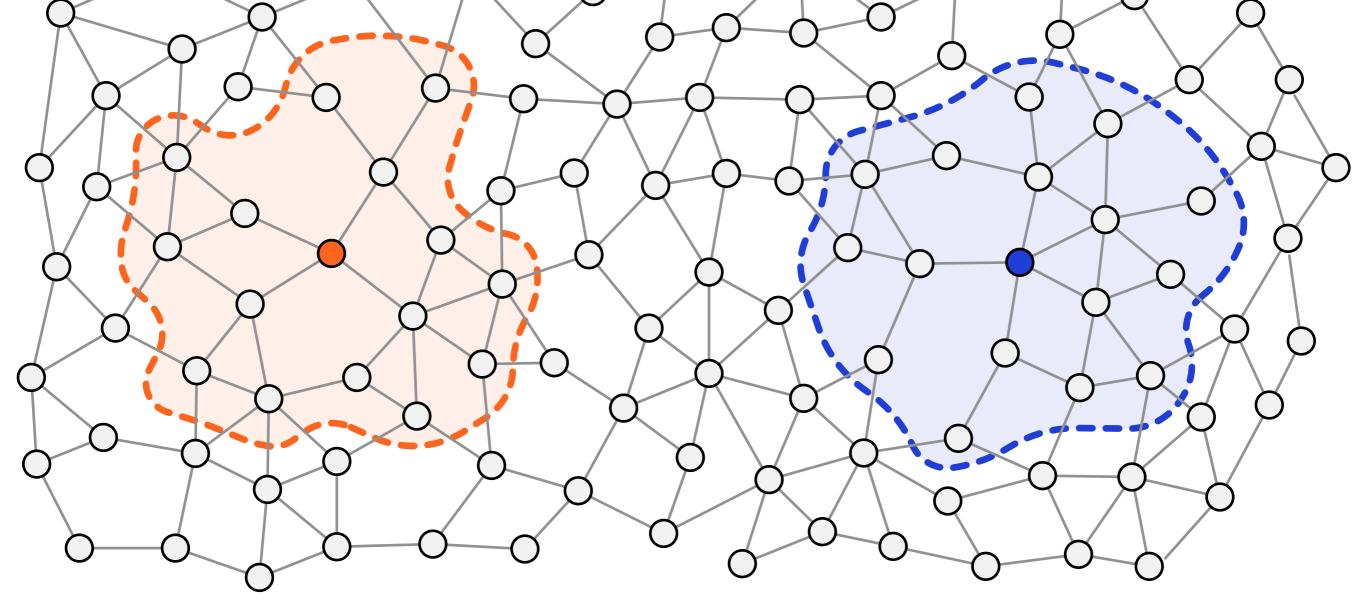
Locality in Networks

- Basic setting:
 - nodes act based on local information only
 - behaviour of node v = function of information available in O(1)-radius neighbourhood of v

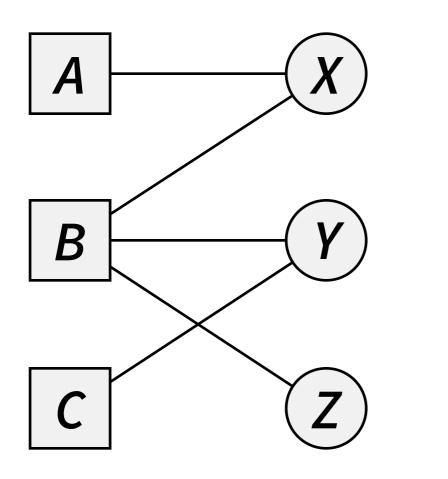
• Question:

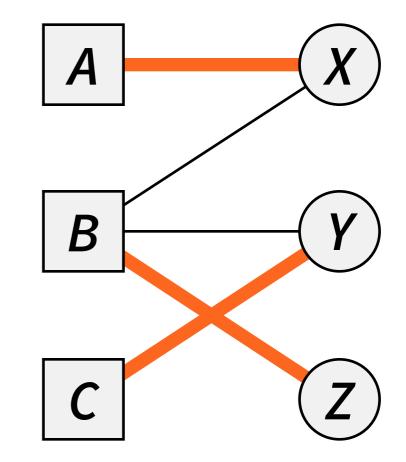
• what tasks can be solved?

Constant-Radius Neighbourhood



Example: Matching in Networks





Example: Matching in Networks

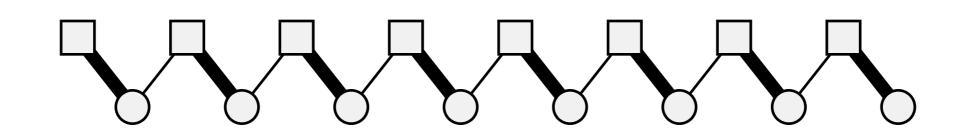
- Job markets: open positions and workers
- Economics: buyers and sellers
- Social networks: marriages
- Computer networks: resource allocation

Local Algorithms for Matching in Networks

- Local perspective:
 - each player decides with whom to pair based on its local neighbourhood
- Global perspective:
 - globally consistent solution, good solution (e.g., large matching)

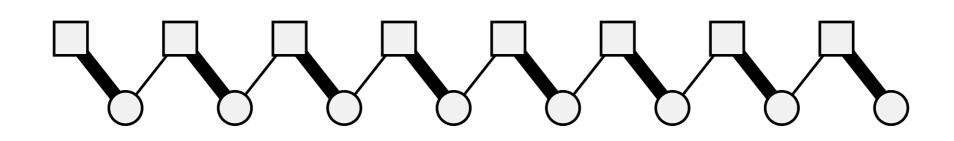
Maximum Matchings

Largest possible number of pairs

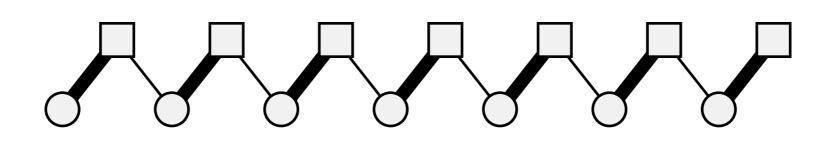


Maximum Matchings

• No local algorithm — simple proof:

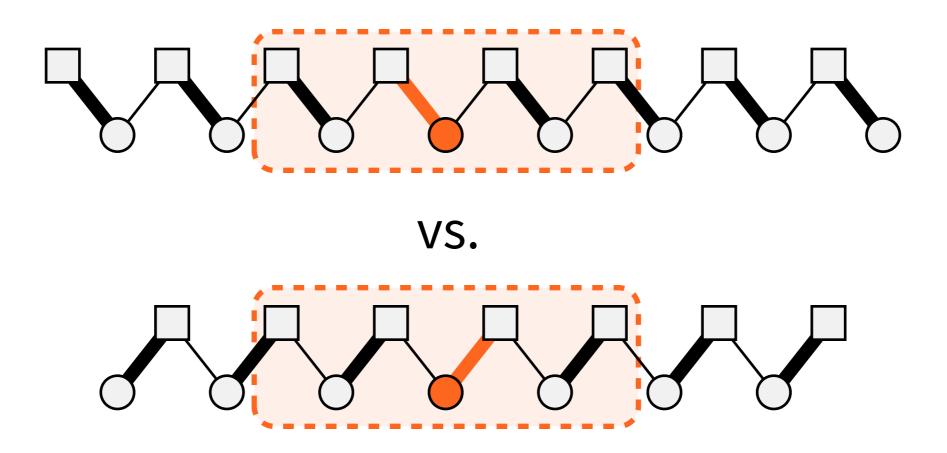


VS.



Maximum Matchings

Same neighbourhood, different output

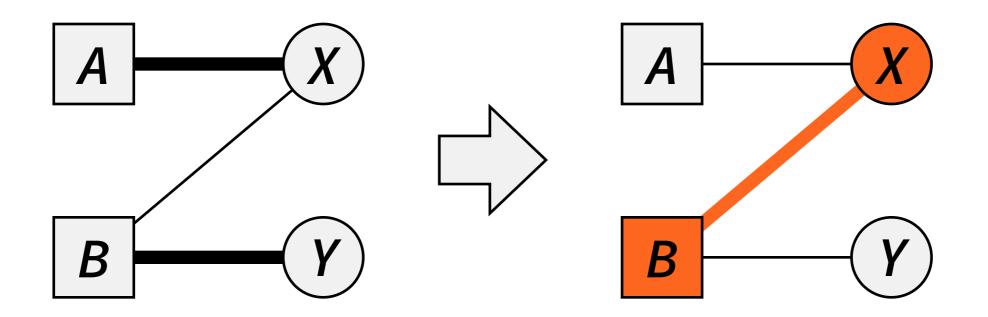


Approximations of Maximum Matchings

- No local algorithm for maximum matching
- However, we can find arbitrarily good approximations locally
 - identify & eliminate all short augmenting paths, in parallel
 - local, if maximum degree O(1)

Stable Matchings

- No pair of nodes has incentive to change
 - X prefers B to A, B prefers X to Y



Stable Matchings

- No pair of nodes has incentive to change
- Not possible with local behaviour
 - long path
 - preferences near endpoints determine what we must do near midpoint

Stable Matchings

- No pair of nodes has incentive to change
- Not possible with local behaviour
- Possible if we tolerate a small fraction of unstable edges
 - simple and natural local algorithm...

Almost Stable Matchings

- Truncated Gale–Shapley algorithm
 - currently unmatched "men" propose women in preference order
 - "women" accept the best proposal so far
 - run for O(1) parallel rounds **local**
- Few unstable edges (if low degrees)

Local Algorithms

- Active subfield of distributed computing
 - Linial (1992):
 "Locality in distributed graph algorithms"
 - Naor & Stockmeyer (1995):
 "What can be computed locally"
 - Kuhn, Moscibroda, Wattenhofer (2004):
 "What cannot be computed locally"

Local Algorithms for Graph Problems

- Lots of good approximations at least in some special cases:
 - matchings, dominating sets, edge covers, vertex covers, packing/covering linear programs, ...
- More details: "Survey of local algorithms" (2013)

2. Network Science Perspective

reasons to expect locality
implications

Why Local?

- Attractive in computer networks
 - fast, fault-tolerant, robust
 - cheap and simple
 - easy to design, easy to implement
- What about social networks, markets, biological systems, industrial systems...?

Why Expect Locality?

- Privacy, competition, selfishness
 - why would strangers reveal what they know?
 - why would our competitors do it?

Timeliness

 distant information is likely outdated, so why care about it at all?

Why Expect Locality?

- Simple and unreliable communication
 - how to encode lots of data in a mixture of some chemical compounds?
- Simple entities, limited capabilities
 - could I keep track of friends of friends of friends?

Implications

- Distributed systems:
 - upper-bound results are of practical use
 - algorithms that we can implement and run
- Network science:
 - lower-bound results are of practical use?
 - learn about possible behaviour in networks

Locality Lower Bounds: Predictions

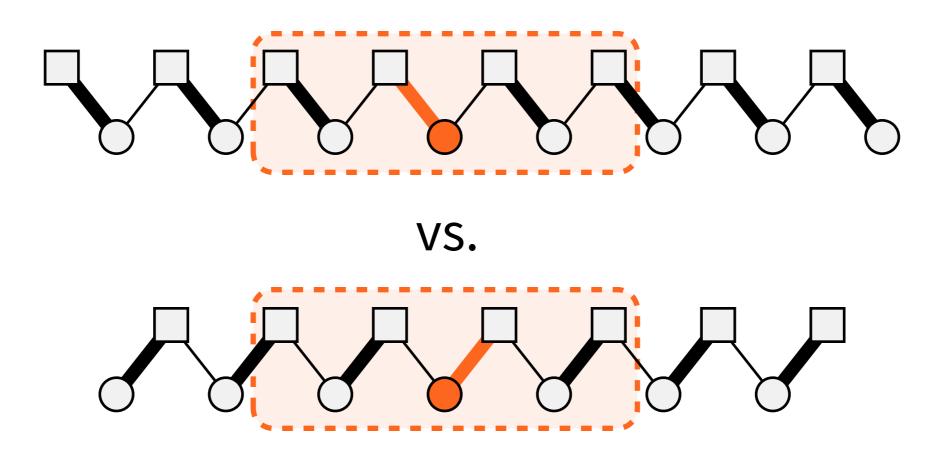
- No good matchings in real-world networks
 - open positions *and* unemployed people
- No optimal resource allocation
- Even if everyone does its best to co-operate!
 - not price of anarchy but price of locality

3. Understanding Locality Lower Bounds

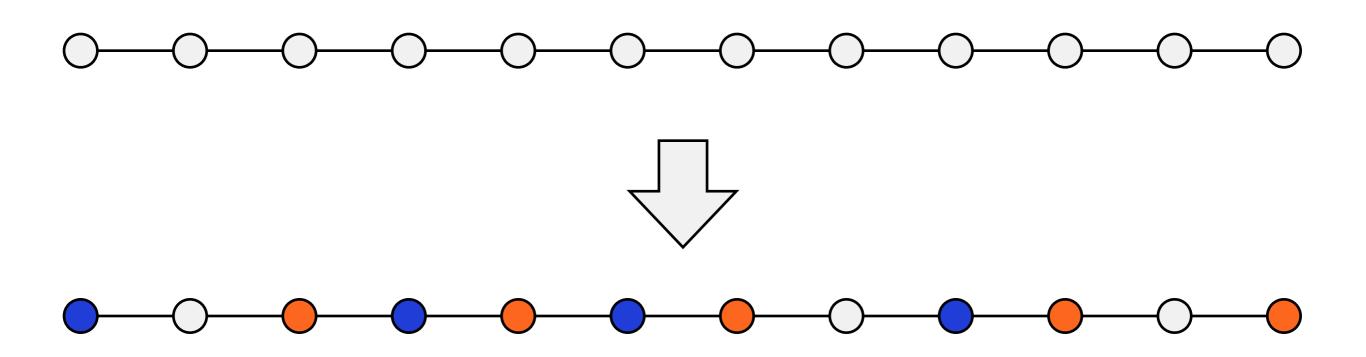
– why are some tasks non-local?

- Common theme:
 - nodes *u* and *v* have identical local neighbourhoods
 - nodes *u* and *v* should make different decisions

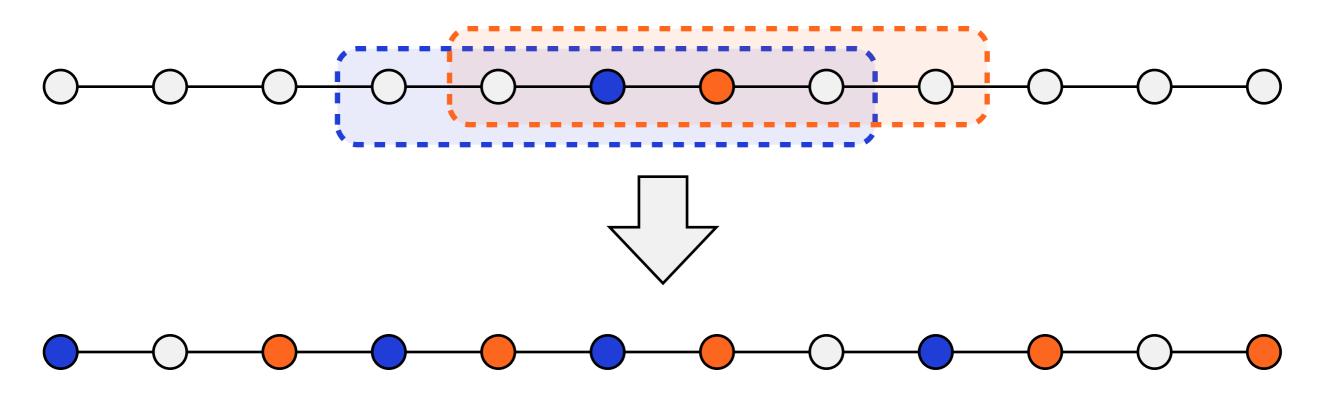
• Example: maximum matching



• Example: graph colouring

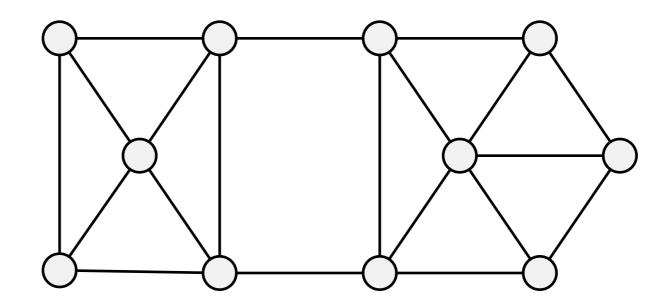


• Example: graph colouring



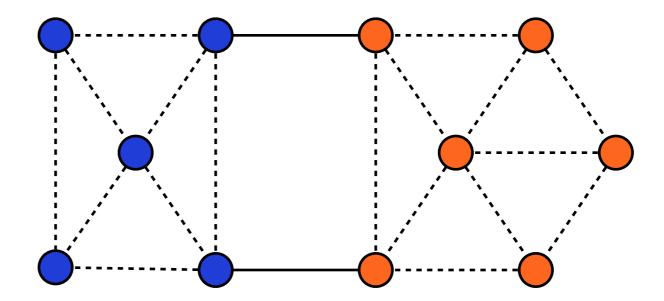
- Maximum matching:
 - global optimum needs global information
- Graph colouring:
 - extra information needed to break symmetry
- But there are also less obvious reasons...

- Label nodes with orange/blue
- Cut edge: endpoints with different colours



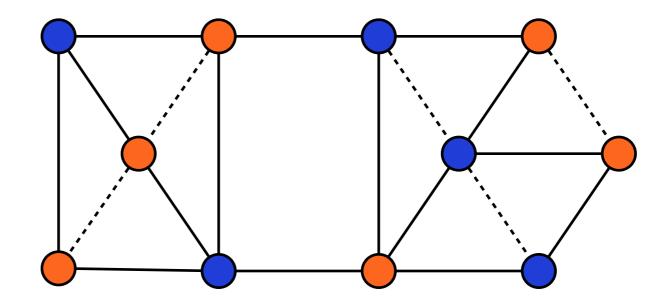
- Label nodes with orange/blue
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Bad solution:



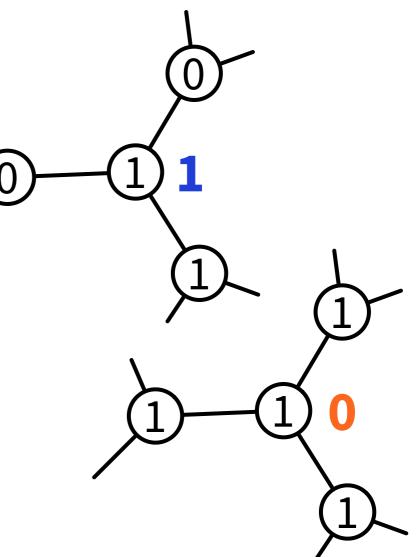
- Label nodes with orange/blue
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Good solution:



- Simple local rule: flip coins to pick labels
 - in expectation 1/2 of all edges are good
 - trivial 1/2-approximation
- Can we do better?
 - what if we looked further?
 - what if we used more random bits?

- We can do *slightly* better:
 - flip coins
 - change mind if "too many" neighbours with the same random bit
 - *d*-regular triangle-free graphs: $1/2 + \Theta(1/\sqrt{d})$
- Best possible approximation ratio why?



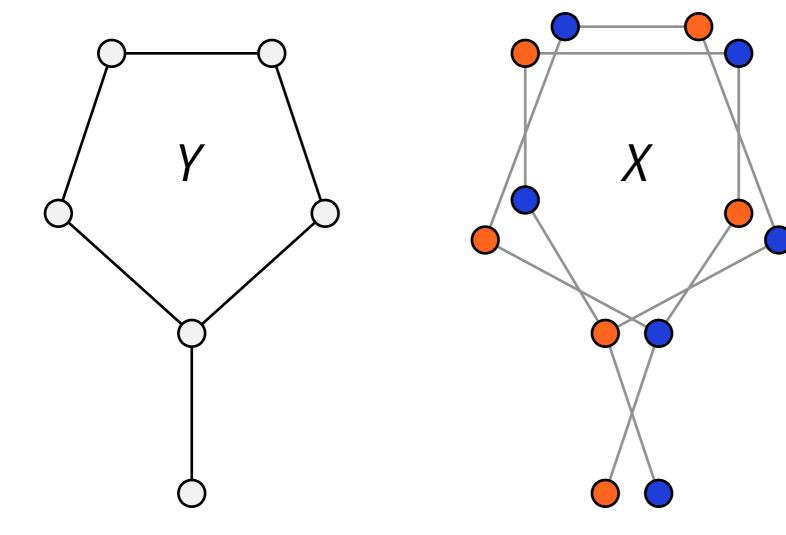
Lower Bound: Large Cuts

- Networks X and Y look locally identical:
 - X has large cuts, Y does not have large cuts
- Local algorithm A: same behaviour in X and Y
 - must produce small cuts in Y
 - therefore produces small cuts in X, too
 - poor approximation ratio in X

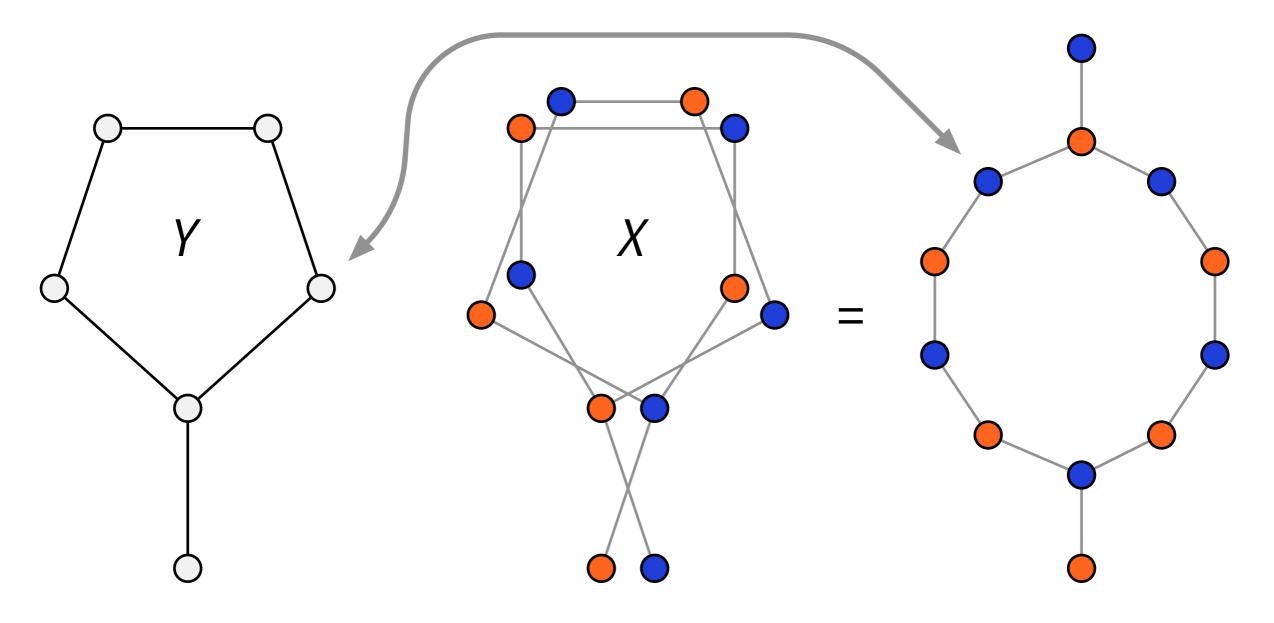
Lower Bound: Large Cuts

- Y = non-bipartite Ramanujan graphs
 - high girth looks locally like a tree
 - no large cuts (spectral properties)
- X = bipartite double cover of Y
 - looks locally identical to Y
 - has a large cut (bipartite)

Bipartite Double Cover



Identical Local Neighbourhoods



Identical Local Neighbourhoods

- Edge *e* in *Y* similar edges *e*₁ and *e*₂ in *X*
- Pr[edge e₁ in X is a cut edge] =
 Pr[edge e₂ in X is a cut edge] =
 Pr[edge e in Y is a cut edge]
- E[fraction of cut edges in X] =
 E[fraction of cut edges in Y]

Reasons for Non-Locality

Similar techniques work for many problems

- find a bad counterexample Y
- construct an "easy" instance X
- make sure X and Y look locally identical
- local algorithm: similar behaviour in X and Y
- poor approximation in X

Typical Counterexamples

• Regular graph

- node degrees do not help
- High girth
 - locally looks like a regular tree
- Expander graphs

4. But What About More Realistic Networks?

 do locality lower bounds tell us anything about "typical" networks?

Locality in Real-World Networks

- Local algorithms for "nice" graph families?
- Some progress:
 - bounded degrees
 - bounded growth, bounded independence...
 - bounded arboricity, forbidden minors...
 - line graphs, planar graphs...

Locality in Real-World Networks

- Distributed computing community focuses on graph families that look like "typical computer networks"
 - bounded degrees ≈ wired networks
 - bounded growth ≈ wireless networks

Locality in Real-World Networks

- Distributed computing community focuses on graph families that look like "typical computer networks"
- What about job markets, biological networks, social networks, ...?
 - need to re-think the assumptions

5. Next Steps

towards tight results in relevant graph families

Research Agenda: Next Steps

- Radius of locality r vs.
 parameters of network family
- State of the art: r vs. maximum degree Δ
 - $r = \Theta(1)$ approximations of max-cut
 - $r = \Theta(\text{polylog } \Delta)$ approximations of LPs
 - $r = \Theta(\Delta)$ maximal solutions to LPs

Research Agenda: Next Steps

- Radius of locality r vs.
 parameters of network family
- Maximum degree:
 - wrong parameter for social networks
 - tight bounds on r in networks with a small number of high-degree nodes?

Summary: Locality in Networks

 how to go beyond the traditional scope of *computer* networks?