- Weeks 1–2: informal introduction
 - network = path



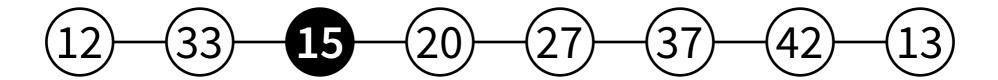
- Week 3: graph theory
- Weeks 4–7: models of computing
 - what can be computed (efficiently)?
- Weeks 8–11: lower bounds
 - what cannot be computed (efficiently)?
- Week 12: recap

Week 2

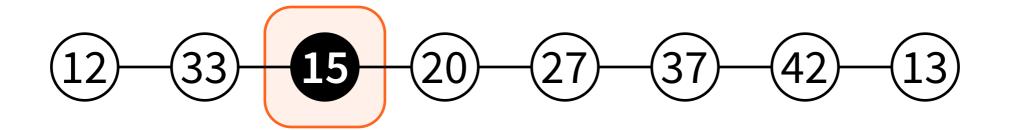
- Warm-up: negative results

- Output of a node can only depend on what it knows
- After T time steps, a node can only know about things up to distance T

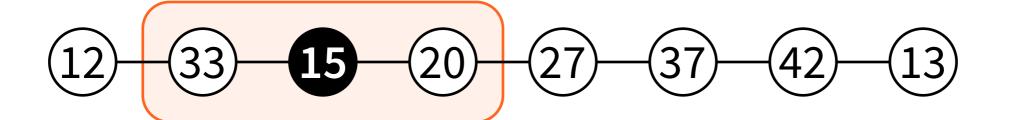
- Who knows that node 15 exists?
 - initially, only node 15
 - everyone else has to learn it by exchanging messages



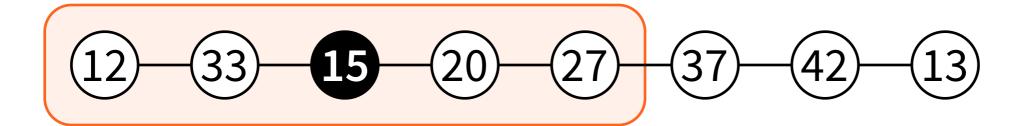
- Who knows about node 15 at time T = 0?
 - initial state, before we exchange any messages



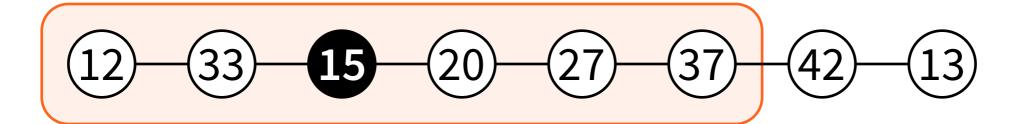
- Who knows about node 15 at time T = 1?
 - after 1 communication round



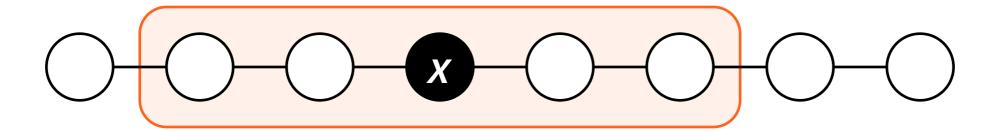
- Who knows about node 15 at time T = 2?
 - after 2 communication rounds



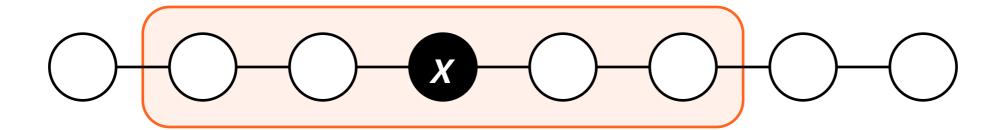
- Who knows about node 15 at time T = 3?
 - after 3 communication rounds



- After T communication rounds, only nodes up to distance T from node x can know anything about node x
 - distance = "number of hops"

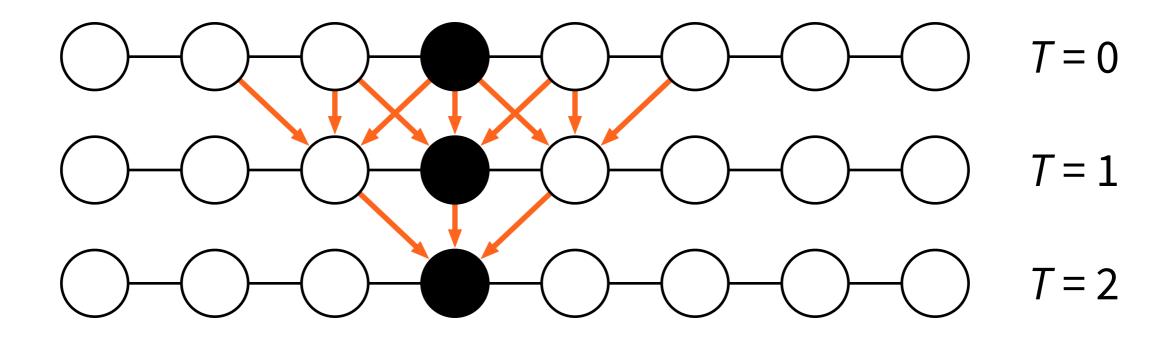


- After T communication rounds, node x can only know about other nodes that are within distance T from it
 - distance = "number of hops"



- My state at time T only depends on:
 - my state at time T − 1, and
 - messages that I received on round T, which only depend on:
 - the state of my neighbours at time T − 1

 State at time T only depends on initial information within distance T



- Time = distance
- Fast algorithm = "local" algorithm
 - outputs only depend on local neighbourhoods

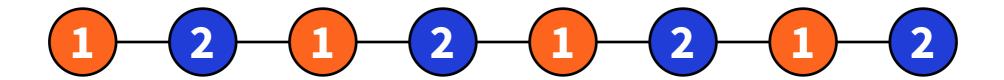
Example: 3-colouring

- Recall: given 128-bit unique identifiers,
 3-colouring possible in 7 rounds
- Equivalently: each node can pick its colour based on what it sees in its radius-7 neighbourhood



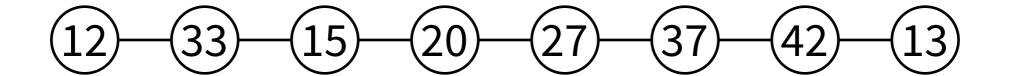
Using locality to prove lower bounds

- Example: 2-colouring of a path
- Upper bound: possible in time O(n)
- Lower bound: not possible in time o(n)

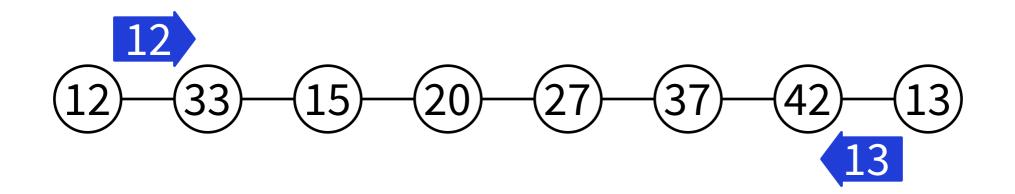


- Assumption: path, unique identifiers
- Two phases:
 - find the endpoint with smaller identifier
 - starting from this end, assign colours
 1, 2, 1, 2, ...

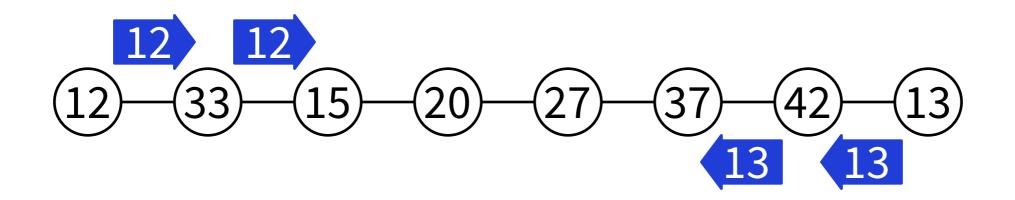
- "ID x" = there is an endpoint with identifier x
- "colour c" = my colour is c



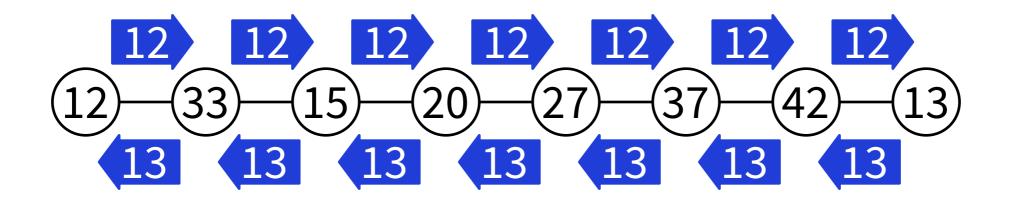
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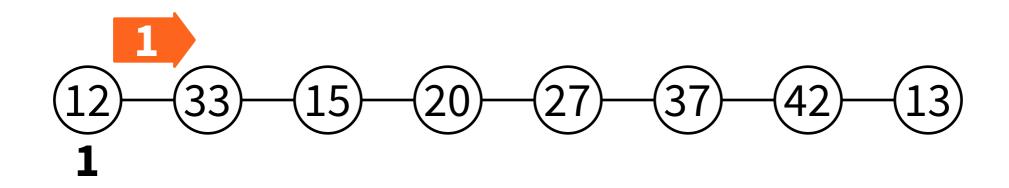
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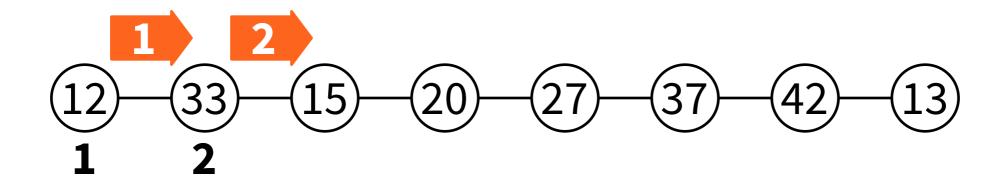
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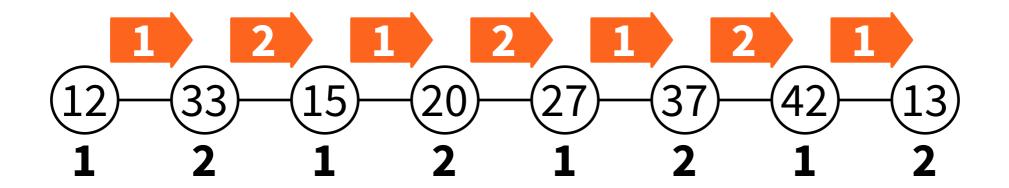
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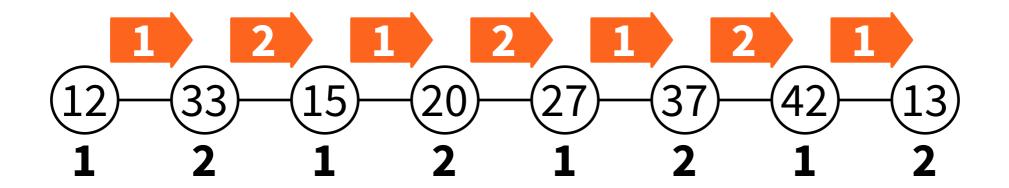
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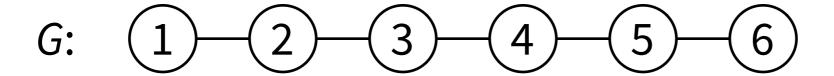
- **States:** "I have have received ID x from left and next I will need to send it to right", ...
- Running time: O(n) rounds



- 2-colouring possible in O(n) rounds
- Goal: prove that this is optimal!
 - there is no algorithm that finds a 2-colouring in time o(n)
 - assumptions: path, unique identifiers

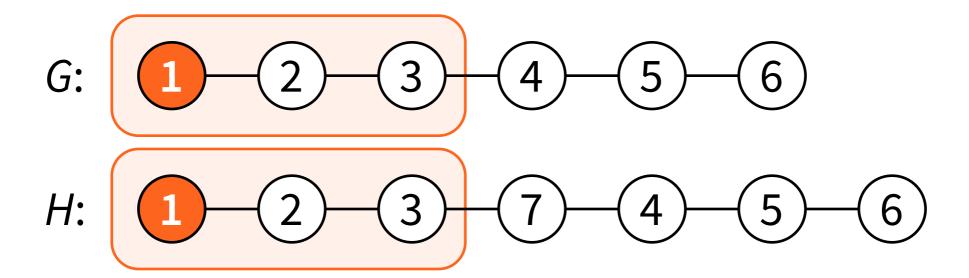
- Assume: there is an o(n)-time algorithm A
- For large n, running time << n/2
- Idea: construct two possible worlds, show that A fails in one of them

• Long paths with 2k and 2k+1 nodes, algorithm runs in $\leq k-1$ rounds

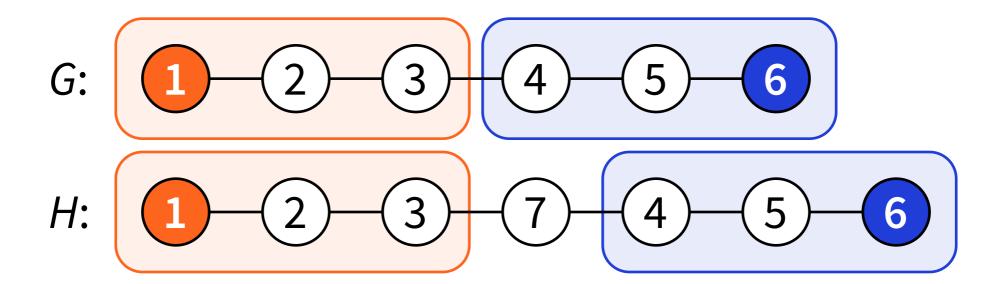


H: (1)-(2)-(3)-(7)-(4)-(5)-(6)

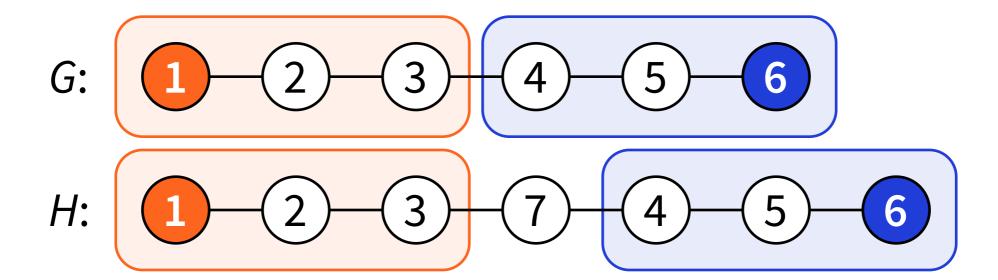
• Same (k-1)-neighbourhood, same output



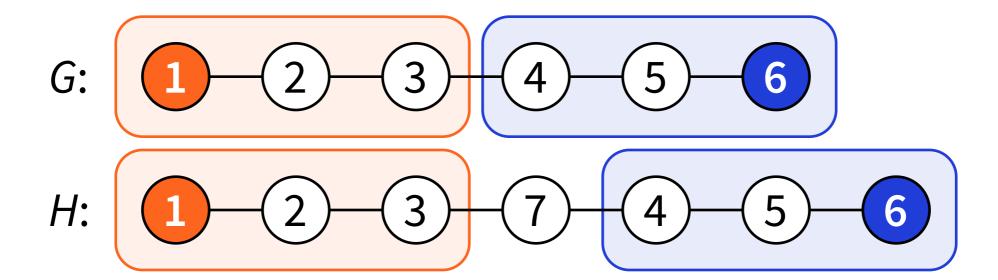
• Same (k-1)-neighbourhood, same output



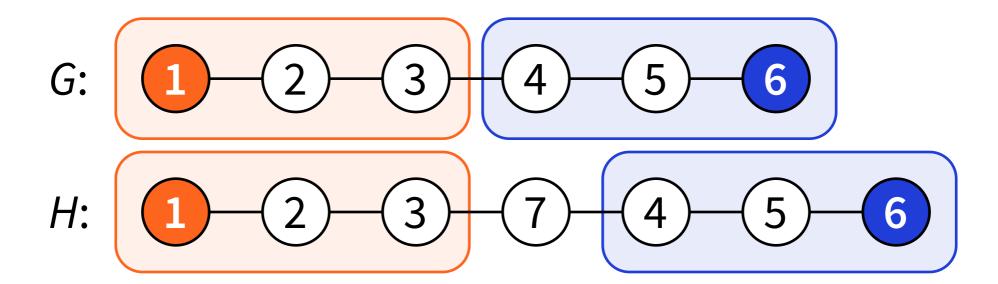
Contradiction — why?



- G: nodes 1 and 6 must have different colours
- H: nodes 1 and 6 must have the same colour

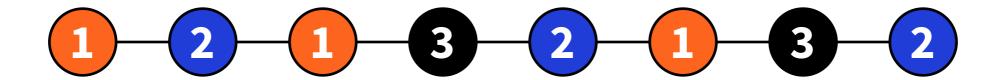


 Conclusion: there is no algorithm that finds a 2-colouring of a path in time o(n)

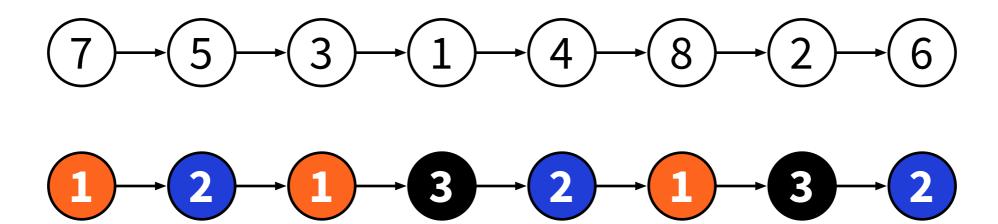


Using locality to prove lower bounds

- Example: 3-colouring of a path
- Upper bound: possible in time O(log* n)
- Lower bound: not possible in time o(log* n)



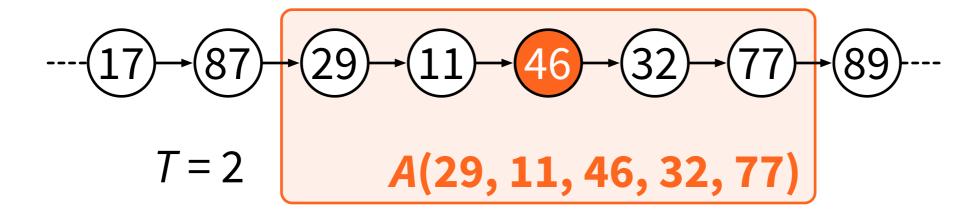
Given: directed path with n nodes,
 identifiers are a permutation of {1, 2, ..., n}



- Given: directed path with n nodes,
 identifiers are a permutation of {1, 2, ..., n}
- Assume: there is an algorithm A that finds a 3-colouring in time T
- Goal: prove that $T \ge \frac{1}{2} \log^*(n) 1$

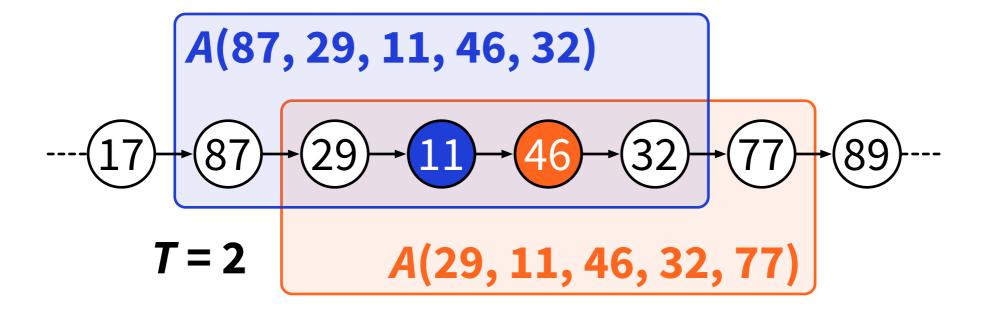
Algorithm for 3-colouring paths

- Running time T = output only depends on radius-T neighbourhood of the node
- Algorithm = k-ary function where k = 2T+1



Algorithm for 3-colouring paths

 $A(87, 29, 11, 46, 32) \neq A(29, 11, 46, 32, 77)$



Algorithm for c-colouring paths

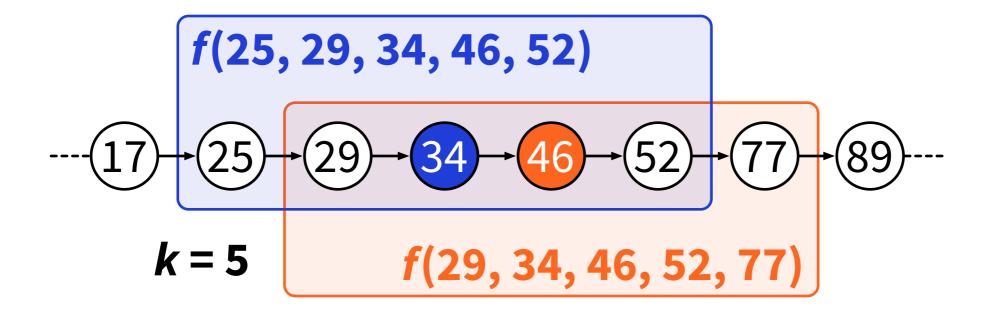
- $A(x_1, ..., x_k) \in \{1, ..., c\}$ for all distinct $x_1, ..., x_k \in \{1, ..., n\}$
- $A(x_1, ..., x_k) \neq A(x_2, ..., x_{k+1})$ for all distinct $x_1, ..., x_{k+1} \in \{1, ..., n\}$

Definition: "k-ary c-colouring function"

- $f(x_1, ..., x_k) \in \{1, ..., c\}$ for all $1 \le x_1 < ... < x_k \le n$
- $f(x_1, ..., x_k) \neq f(x_2, ..., x_{k+1})$ for all $1 \leq x_1 < ... < x_{k+1} \leq n$
- We only care what happens with increasing identifiers

k-ary c-colouring function

 $f(25, 29, 34, 46, 52) \neq f(29, 34, 46, 52, 77)$



k-ary c-colouring function

- Assume: A is a distributed algorithm that finds a 3-colouring in directed n-cycles in time T
- Then: A is also a k-ary 3-colouring function for k = 2T + 1
- Plan: show that $k + 1 \ge \log^* n$

Lemma 1

• If f is a 1-ary c-colouring function, then $c \ge n$

Proof:

- pigeonhole principle
- if c < n, there is a collision f(x) = f(y) for some $1 \le x < y \le n$, contradiction

Lemma 2

- If f is a k-ary c-colouring function, then we can construct a (k-1)-ary 2^c -colouring function g
- Proof:
 - $g'(x_1, ..., x_{k-1}) = \{f(x_1, ..., x_{k-1}, y) : y > x_{k-1}\}$
 - $g(x_1, ..., x_{k-1}) = h(g'(x_1, ..., x_{k-1}))$
 - h = bijection that maps sets to colours

- $g'(x_1, ..., x_{k-1}) = \{f(x_1, ..., x_{k-1}, y) : y > x_{k-1}\}$
- $g(x_1,...,x_{k-1}) = h(g'(x_1,...,x_{k-1}))$
- h = bijection that maps sets to colours
- By construction: $g(x_1, ..., x_{k-1}) \in \{1, ..., 2^c\}$
- Need to show: $g(x_1, ..., x_{k-1}) \neq g(x_2, ..., x_k)$ for all $1 \leq x_1 < ... < x_k \leq n$

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•
$$g'(x_1, ..., x_{k-1}) = \{f(x_1, ..., x_{k-1}, y) : y > x_{k-1}\}$$

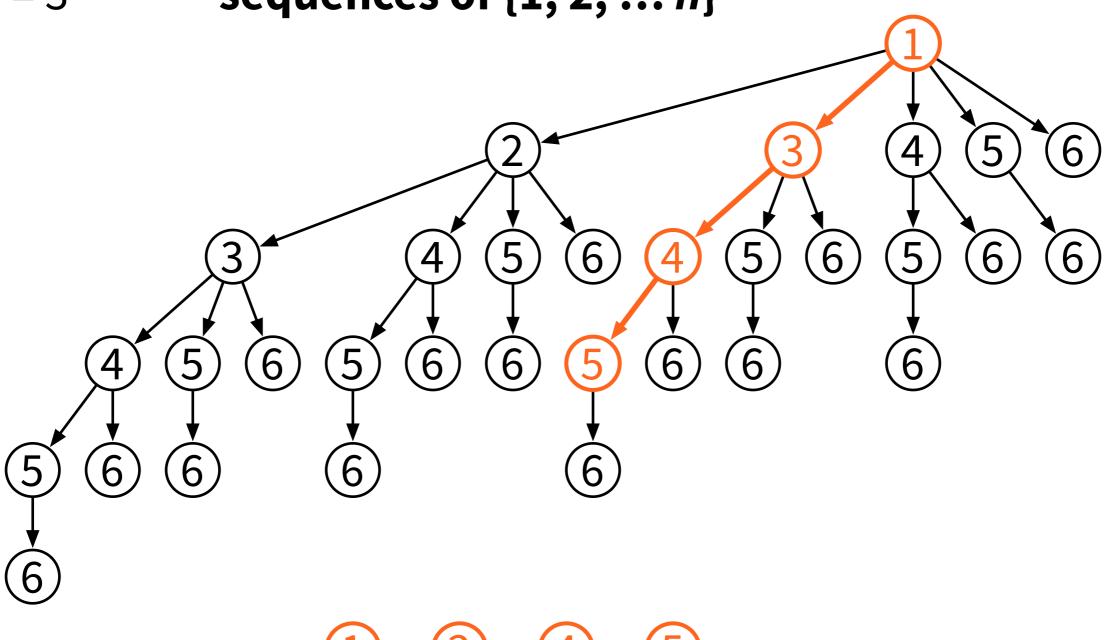
• Need to show: $g'(x_1, ..., x_{k-1}) \neq g'(x_2, ..., x_k)$ for all $1 \leq x_1 < ... < x_k \leq n$

- $1 \le x_1 < x_2 < \dots < x_k \le n$
- $g'(x_1, ..., x_{k-1}) = \{f(x_1, ..., x_{k-1}, y) : y > x_{k-1}\}$
- $g'(x_2, ..., x_k) = \{f(x_2, ..., x_k, z) : z > x_k\}$
- $f(x_1, ..., x_{k-1}, x_k) \in g'(x_1, ..., x_{k-1})$
- $f(x_1, ..., x_{k-1}, x_k) \notin g'(x_2, ..., x_k)$
- $g'(x_1, ..., x_{k-1}) \neq g'(x_2, ..., x_k)$

- $1 \le x_1 < x_2 < \dots < x_k \le n$
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- $f(x_1, ..., x_{k-1}, x_k) \notin g'(x_2, ..., x_k)$
- $g(x_1,...,x_{k-1}) \neq g(x_2,...,x_k)$

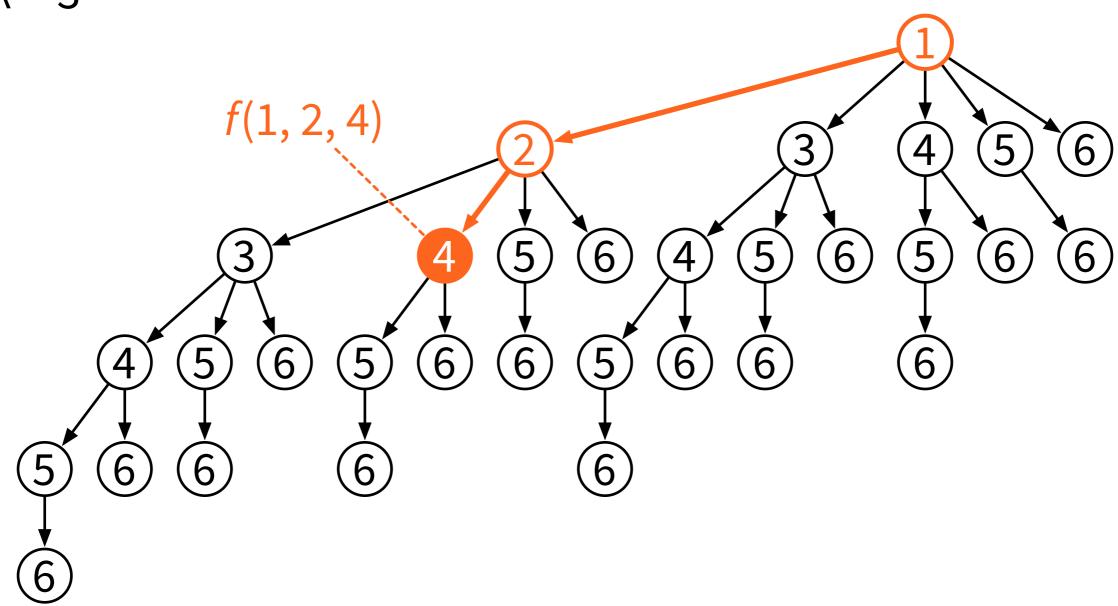
$$n = 6$$
$$k = 3$$

Tree that contains all increasing sequences of $\{1, 2, ..., n\}$

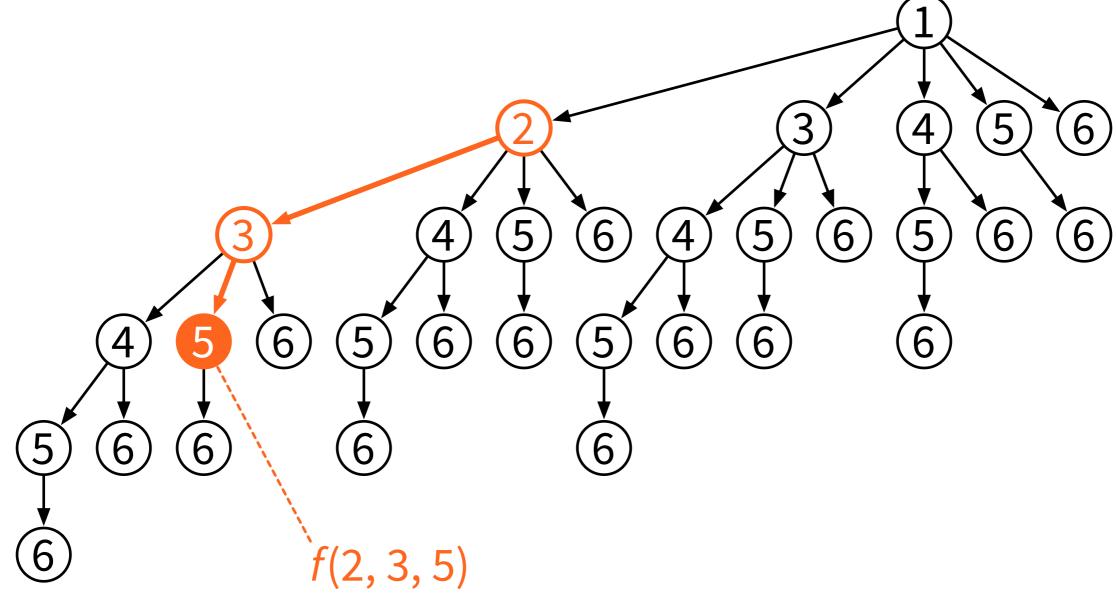


$$\boxed{1 \rightarrow 3 \rightarrow 4 \rightarrow 5}$$

$$n = 6$$
 Colour of a node = value of f $k = 3$



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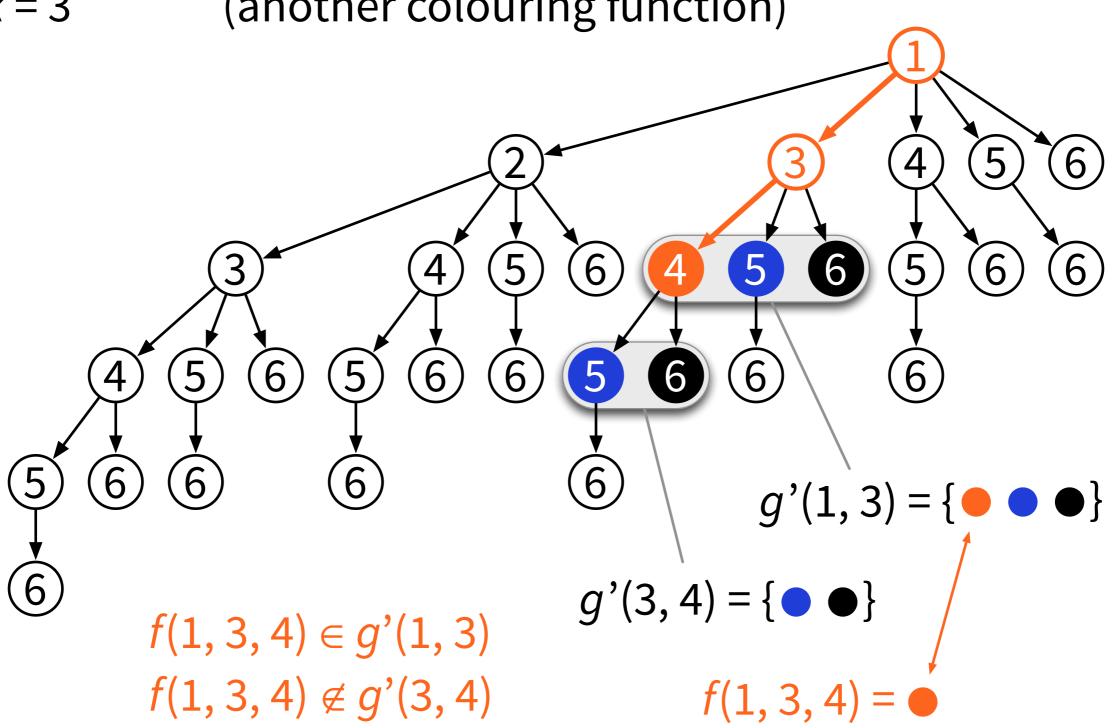
Colour of a node = value of f n = 6(colouring function) k = 3(6)(6)f(2,3,5)f(3, 5, 6)

Colour of a node = value of f n = 6(colouring function) k = 3(6)(6)6 f(3, 4, 5)

$$n = 6$$

Colours of all children = value of g

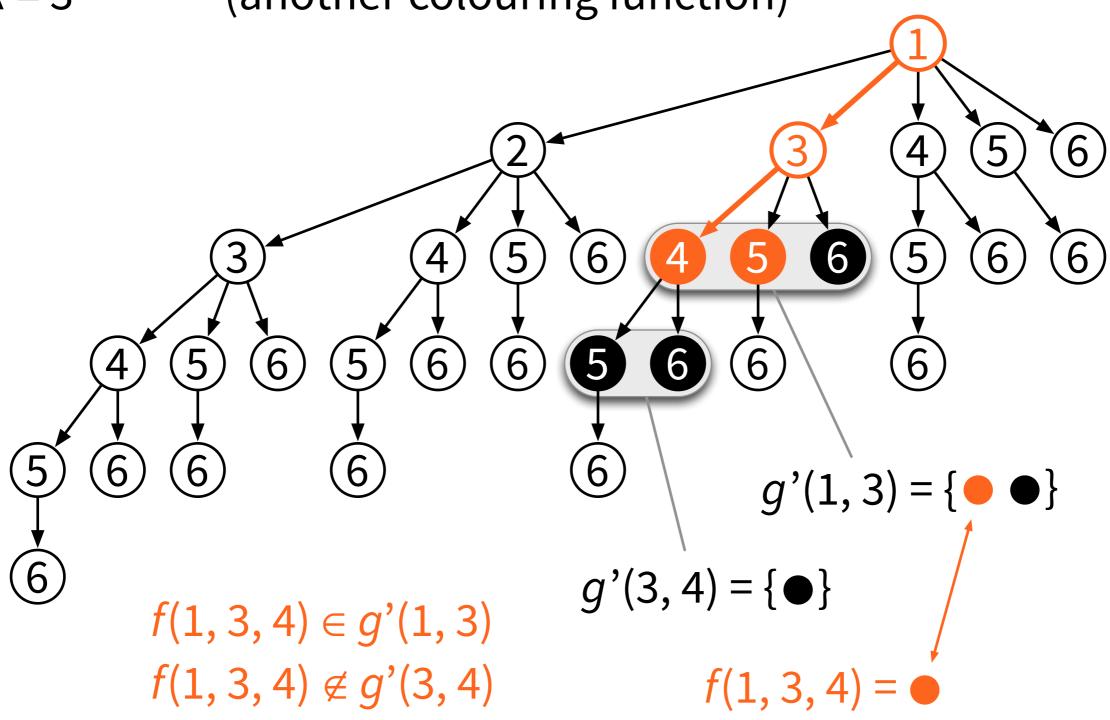
k = 3(another colouring function)



$$n = 6$$

Colours of all children = value of g

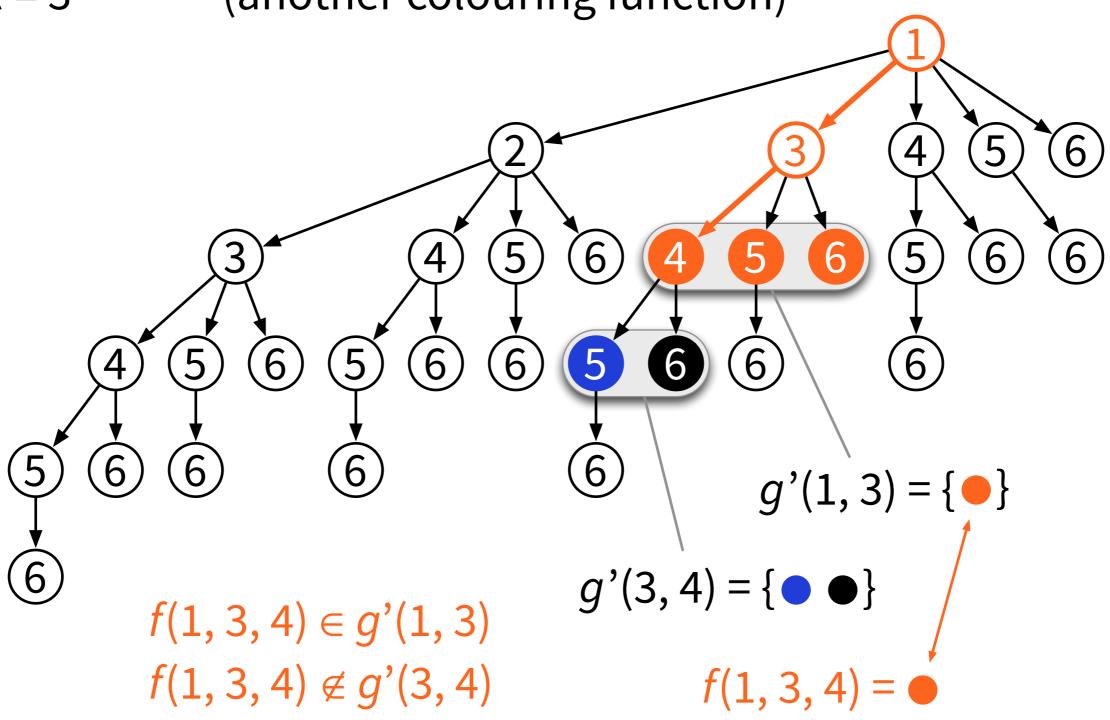
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$$n = 6$$

Colours of all children = value of g

k = 3 (another colouring function)



Lemma 2

• If f is a k-ary c-colouring function, then we can construct a (k-1)-ary 2^c -colouring function g

Proof:

- $g'(x_1, ..., x_{k-1}) = \{f(x_1, ..., x_{k-1}, y) : y > x_{k-1}\}$
- $g(x_1, ..., x_{k-1}) = h(g'(x_1, ..., x_{k-1}))$
- h = bijection that maps sets to colours

Iterate Lemma 2

$$^{i}2 = 2^{2} \cdot (i \text{ twos})$$

```
    k-ary 3-colouring function ⇒
    k-ary <sup>2</sup>2-colouring function ⇒
    (k-1)-ary <sup>3</sup>2-colouring function ⇒
    (k-2)-ary <sup>4</sup>2-colouring function ⇒
    (k-3)-ary <sup>5</sup>2-colouring function ⇒
    1-ary <sup>k+1</sup>2-colouring function
```

Lemma 1 + Lemma 2

$$^{i}2 = 2^{2} \cdot (i \text{ twos})$$

Lemma 2:

- k-ary 3-colouring function →
 1-ary k+1/2-colouring function
- Lemma 1:
 - $^{k+1}2 \ge n$ (that is, $k+1 \ge \log^* n$)

Lower bound for 3-colouring

- Assume: A is a distributed algorithm that finds a 3-colouring in directed n-cycles in time T
- Then: A is also a k-ary 3-colouring function for k = 2T + 1
- Then: k + 1 ≥ log* n,
 therefore: T ≥ ½ log*(n) 1

Conclusions: tight bounds

2-colouring paths:

- possible in time O(n)
- not possible in time o(n)

• 3-colouring paths:

- possible in time O(log* n)
- not possible in time o(log* n)

Assuming: directed path, unique IDs = {1, 2, ..., n}

Conclusions: tight bounds

2-colouring paths:

- possible in time O(n)
- not possible in time o(n)

• 3-colouring paths:

possible in time O(log* n)

Richard Cole and Uzi Vishkin (1986)

not possible in time o(log* n)

Nathan Linial (1992)

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